


# Existence of positive solutions for a nonlinear semipositone boundary value problems on a time scale

SAROJ PANIGRAHI<sup>1</sup>, 

SANDIP ROUT<sup>1</sup> 

<sup>1</sup> School of Mathematics and Statistics,  
University of Hyderabad, Hyderabad,  
500 046, India.  
[panigrahi2008@gmail.com](mailto:panigrahi2008@gmail.com)   
[sandiprout7@gmail.com](mailto:sandiprout7@gmail.com)

## ABSTRACT

In this paper, we are concerned with the existence of positive solution of the following semipositone boundary value problem on time scales:

$$(\psi(t)y^\Delta(t))^\nabla + \lambda_1 g(t, y(t)) + \lambda_2 h(t, y(t)) = 0, \quad t \in [\rho(c), \sigma(d)]_{\mathbb{T}},$$

with mixed boundary conditions

$$\begin{aligned}\alpha y(\rho(c)) - \beta \psi(\rho(c)) y^\Delta(\rho(c)) &= 0, \\ \gamma y(\sigma(d)) + \delta \psi(d) y^\Delta(d) &= 0,\end{aligned}$$

where  $\psi : C[\rho(c), \sigma(d)]_{\mathbb{T}}, \psi(t) > 0$  for all  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ ; both  $g$  and  $h : [\rho(c), \sigma(d)]_{\mathbb{T}} \times [0, \infty) \rightarrow \mathbb{R}$  are continuous and semipositone. We have established the existence of at least one positive solution or multiple positive solutions of the above boundary value problem by using fixed point theorem on a cone in a Banach space, when  $g$  and  $h$  are both superlinear or sublinear or one is superlinear and the other is sublinear for  $\lambda_i > 0; i = 1, 2$  are sufficiently small.

### RESUMEN

En este artículo estudiamos la existencia de soluciones positivas del siguiente problema de valor de frontera semipositón en escalas de tiempo:

$$(\psi(t)y^\Delta(t))^\nabla + \lambda_1 g(t, y(t)) + \lambda_2 h(t, y(t)) = 0, \quad t \in [\rho(c), \sigma(d)]_{\mathbb{T}},$$

con condiciones de frontera mixtas

$$\begin{aligned}\alpha y(\rho(c)) - \beta \psi(\rho(c)) y^\Delta(\rho(c)) &= 0, \\ \gamma y(\sigma(d)) + \delta \psi(d) y^\Delta(d) &= 0,\end{aligned}$$

donde  $\psi : C[\rho(c), \sigma(d)]_{\mathbb{T}}, \psi(t) > 0$  para todo  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ ; ambas  $g$  y  $h : [\rho(c), \sigma(d)]_{\mathbb{T}} \times [0, \infty) \rightarrow \mathbb{R}$  son continuas y semipositón. Hemos establecido la existencia de al menos una solución positiva o múltiples soluciones positivas del problema de valor en la frontera anterior usando un teorema de punto fijo en un cono en un espacio de Banach, cuando  $g$  y  $h$  son ambas superlineales o sublineales o una es superlineal y la otra es sublineal para  $\lambda_i > 0; i = 1, 2$  suficientemente pequeños.

**Keywords and Phrases:** Positive solutions, boundary value problems, fixed point theorem, cone, time scales.

**2020 AMS Mathematics Subject Classification:** 34B15, 34B16, 34B18, 34N05, 39A10, 39A13.



# 1 Introduction

The study of dynamic equations on time scales goes to the seminal work of Stefan Hilger [11] and has received a lot of attention in recent years. Time scales were created to unify the study of continuous and discrete mathematics and particularly used in differential and difference equations. We are interested to prove the results for a dynamic equation where the domain of the unknown function is a time scale  $\mathbb{T}$ , which is a non-empty closed subset of real numbers  $\mathbb{R}$ .

We consider the second order semipositone boundary value problem on time scales:

$$(\psi(t)y^\Delta(t))^\nabla + \lambda_1 g(t, y(t)) + \lambda_2 h(t, y(t)) = 0, \quad t \in [\rho(c), \sigma(d)]_{\mathbb{T}}, \tag{1.1}$$

with mixed boundary conditions

$$\begin{aligned} \alpha y(\rho(c)) - \beta \psi(\rho(c))y^\Delta(\rho(c)) &= 0, \\ \gamma y(\sigma(d)) + \delta \psi(d)y^\Delta(d) &= 0, \end{aligned} \tag{1.2}$$

where  $\lambda_1$  and  $\lambda_2$  are positive and

(H<sub>1</sub>)  $\psi : C[\rho(c), \sigma(d)]_{\mathbb{T}}, \psi(t) > 0$  for all  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ ;

(H<sub>2</sub>)  $\alpha, \beta, \gamma, \delta, \geq 0$  and  $\alpha\delta + \beta\gamma + \alpha\gamma > 0$ ;

(H<sub>3</sub>)  $g$  and  $h : [\rho(c), \sigma(d)]_{\mathbb{T}} \times [0, \infty) \rightarrow \mathbb{R}$  are continuous satisfying with both  $g$  and  $h$  are semipositone.

D. R. Anderson and P. Y. Wong [1], have established the existence result for the SL-BVP (1.1) and (1.2) where  $g$  is superlinear such that  $g(t, y) \geq -M$  for some constant  $M > 0$  and  $\lambda$  is in some interval of  $\mathbb{R}$  with  $h(t, y) = 0$ . They did not establish any results concerning the existence of positive solutions for the boundary value problem (1.1) and (1.2), when  $g$  is sublinear. Many findings have also been obtained for the existence of positive solution of the boundary value problem (1.1) and (1.2), when  $h(t, y) = 0$ , but only a few results have been established for the existence of positive solutions when  $h(t, y) \neq 0$ . Motivated by the work of [1] and the references cited therein, we would like to establish the sufficient conditions for the existence of positive solution of the boundary value problem (1.1) and (1.2), when  $g$  and  $h$  are both superlinear or sublinear or one is superlinear and the other is sublinear for  $\lambda_i > 0; i = 1, 2$  are sufficiently small.

It is worthy of mention that results of this paper not only apply to the set of real numbers or the set of integers but also to more general time scales such as  $\mathbb{T} = \mathbb{N}_0^2 = \{t^2 : t \in \mathbb{N}_0\}$ ,  $\mathbb{T} = \{\sqrt{n} : n \in \mathbb{N}_0\}$ , etc. For basic notations and concepts on time scale calculus, we refer the readers to monographs [5, 6] and references cited therein. The study of nonlinear, semipositone boundary value problem has considerable importance even in differential equations. In recent years, several researchers studied

semipositone boundary value problem on time scales [1, 2, 4, 7, 10, 16, 17]. Semipositone problems arise in many physical and chemical processes such as in chemical reactor theory, astrophysics, gas dynamics and fluidmechanics, relativistic mechanics, nuclear physics, design of suspension bridges, bulking of mechanical systems, combustion and management of natural resources (see [3, 9, 12, 15]). Let  $a$  and  $b$  such that  $0 \leq \rho(a) \leq a < b \leq \sigma(b) < \infty$  and  $(\rho(a), \sigma(b))_{\mathbb{T}}$  has at least two points.

The plan of the paper is as follows. In Section 2, we provided some preliminary results concerning the Green's function for the homogeneous boundary value problem and some important Lemmas. These results allow us in Section 3 to discuss the existence of at least one or multiple positive solutions. Finally, in Section 4, we illustrate few examples to justify the results obtained in the previous section.

## 2 Preliminaries

In this section, we have obtained some basic results related to Green's function for the homogeneous boundary value problem and some important Lemmas.

Now let us consider the homogeneous dynamic boundary value problem

$$(\psi(t)y^{\Delta}(t))^{\nabla} = 0, \quad t \in [\rho(c), \sigma(d)]_{\mathbb{T}}, \quad (2.1)$$

with boundary conditions (1.2). Green's function  $\mathcal{G}(t, s)$  (see [7]) for the boundary value problem (2.1) and with the boundary conditions (1.2) is given by

$$\mathcal{G}(t, s) = \frac{1}{\varphi} \begin{cases} \left( \beta + \alpha \int_{\rho(c)}^t \frac{\nabla \tau}{\psi(\tau)} \right) \left( \delta + \gamma \int_s^{\sigma(d)} \frac{\nabla \tau}{\psi(\tau)} \right), & \rho(c) \leq t \leq s \leq \sigma(d), \\ \left( \beta + \alpha \int_{\rho(c)}^s \frac{\nabla \tau}{\psi(\tau)} \right) \left( \delta + \gamma \int_t^{\sigma(d)} \frac{\nabla \tau}{\psi(\tau)} \right), & \rho(a) \leq s \leq t \leq \sigma(b), \end{cases} \quad (2.2)$$

where

$$\varphi = \alpha\delta + \beta\gamma + \alpha\gamma \int_{\rho(c)}^{\sigma(d)} \frac{\nabla \tau}{\psi(\tau)} > 0.$$

**Lemma 2.1** ([17]). *Assume  $(H_1)$  and  $(H_2)$  hold. Then the Green function  $\mathcal{G}(t, s)$  satisfies*

$$(\psi(t)y^{\Delta}(t))^{\nabla} + Q(t) = 0, \quad t \in (\rho(c), \sigma(d))_{\mathbb{T}}, \quad (2.3)$$

with mixed boundary conditions (1.2), where  $Q \in C_{rd}[\rho(c), \sigma(d)]_{\mathbb{T}}$ ,  $Q(t) \geq 0$ ; then

$$y(t) \geq q(t)\|y\|, \quad t \in [\rho(c), \sigma(d)]_{\mathbb{T}}, \quad s \in [a, b]_{\mathbb{T}}, \quad (2.4)$$

where  $q(t)$  is given by

$$q(t) = \min \left\{ \frac{\beta + \alpha \int_{\rho(c)}^t \frac{\nabla\tau}{\psi(\tau)}}{\beta + \alpha \int_{\rho(c)}^{\sigma(d)} \frac{\nabla\tau}{\psi(\tau)}}, \frac{\delta + \gamma \int_t^{\sigma(d)} \frac{\nabla\tau}{\psi(\tau)}}{\delta + \gamma \int_{\rho(c)}^{\sigma(d)} \frac{\nabla\tau}{\psi(\tau)}} \right\}.$$

**Lemma 2.2** ([1]). For all  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$  and  $s \in [c, d]_{\mathbb{T}}$ , then

$$q(t)\mathcal{G}(s, s) \leq \mathcal{G}(t, s) \leq \mathcal{G}(s, s), \tag{2.5}$$

where  $\mathcal{G}(t, s)$  is given in (2.2) and  $q(t)$  is defined as in Lemma 2.1.

**Lemma 2.3** ([1]). Let  $(H_1)$  and  $(H_2)$  hold and let  $y_1$  be the solution of

$$(\psi(t)y^\Delta(t))^\nabla + 1 = 0, t \in (\rho(c), \sigma(d))_{\mathbb{T}}, \tag{2.6}$$

with mixed boundary conditions (1.2), then there exists a positive constant  $C$  such that

$$y_1(t) \leq C q(t), t \in [\rho(c), \sigma(d)]_{\mathbb{T}}, \tag{2.7}$$

where

$$C = \frac{1}{\varphi}(\sigma(d) - \rho(c)) \left( \beta + \alpha \int_{\rho(c)}^{\sigma(d)} \frac{\nabla\tau}{\psi(\tau)} \right) \left( \delta + \gamma \int_{\rho(c)}^{\sigma(d)} \frac{\nabla\tau}{\psi(\tau)} \right).$$

**Lemma 2.4** ([8]). Let  $\lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = \infty$  and define  $\mathbb{G} : [0, \infty) \rightarrow [0, \infty)$  by

$$\mathbb{G} = \max_{\rho(c) \leq t \leq \sigma(d), 0 \leq y \leq r} g(t, y). \tag{2.8}$$

Then

- (I)  $\mathbb{G}$  is non-decreasing;
- (II)  $\lim_{r \rightarrow \infty} \frac{\mathbb{G}(r)}{r} = \infty$ ;
- (III) there exists  $r^* > 0$  such that  $\mathbb{G}(r) > 0$  for  $r \geq r^*$ .

**Lemma 2.5** ([8]). Let  $\lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = 0$  holds. Then  $\mathbb{G}$  defined by (2.8) is a nondecreasing function, such that

$$\lim_{r \rightarrow \infty} \frac{\mathbb{G}(r)}{r} = 0.$$

Define a function for  $y \in C[\rho(c), \sigma(d)]_{\mathbb{T}}$ ,

$$\bar{g}(t, y) = \begin{cases} g(t, y), & y \geq 0, \\ g(t, 0), & y < 0. \end{cases}$$

and

$$\bar{h}(t, y) = \begin{cases} h(t, y), & y \geq 0, \\ h(t, 0), & y < 0. \end{cases}$$

Let us consider the nonlinear boundary value problem:

$$(\psi(t)y^\Delta)^\nabla = -[\lambda_1 \bar{g}(t, y - x) + \lambda_2 \bar{h}(t, y - x) + M], \quad (2.9)$$

with boundary conditions (1.2).

**Lemma 2.6.** *Assume that  $x(t) = My_1(t)$ , where  $y_1(t)$  is a unique solution of the boundary value problem (2.6) and (1.2). Then  $y(t)$  is a solution of the boundary value problem (1.1) and (1.2) if and only if  $\bar{y}(t) = y(t) + x(t)$  is a positive solution of the boundary value problem (2.9) and (1.2) with  $\bar{y}(t) > x(t)$  for  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ .*

*Proof.* Let us assume that  $\bar{y}(t)$  is a solution of the boundary value problem (2.9) and (1.2) such that  $\bar{y}(t) \geq x(t)$  for any  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ . Let  $y(t) = \bar{y}(t) - x(t) > 0$  on  $[\rho(c), \sigma(d)]_{\mathbb{T}}$  as  $\bar{y}(t) \geq x(t)$ . Now, for any  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ , we have

$$(\psi(t)\bar{y}^\Delta(t))^\nabla + [\lambda_1 \bar{g}(t, (\bar{y}(t) - x(t)) + \lambda_2 \bar{h}(t, (\bar{y}(t) - x(t))) + M] = 0,$$

that is,

$$(\psi(t)y^\Delta(t))^\nabla + (\psi(t)x^\Delta(t))^\nabla + [\lambda_1 \bar{g}(t, (\bar{y}(t) - x(t)) + \lambda_2 \bar{h}(t, (\bar{y}(t) - x(t))) + M] = 0.$$

By using the definition of  $y$  together with the definition of  $x$ , we have

$$(\psi(t)y^\Delta(t))^\nabla + [\lambda_1 \bar{g}(t, y(t)) + \lambda_2 \bar{h}(t, y(t)) + M] + M(\psi(t)y_1^\Delta(t))^\nabla(t) = 0.$$

Thus,

$$(\psi(t)y^\Delta(t))^\nabla + \lambda_1 \bar{g}(t, y(t)) + \lambda_2 \bar{h}(t, y(t)) = 0.$$

On the other hand,

$$\begin{aligned} & \alpha y(\rho(c)) - \beta \psi(\rho(c))y(\rho(c)) \\ &= (\alpha \bar{y}(\rho(c)) - \beta \psi(\rho(c))\bar{y}^\Delta(\rho(c))) - (\alpha x(\rho(c)) - \beta \psi(\rho(c))x^\Delta(\rho(c))) \\ &= (\alpha \bar{y}(\rho(c)) - \beta \psi(\rho(c))\bar{y}^\Delta(\rho(c))) - M(\alpha y_1(\rho(c)) - \beta \psi(\rho(c))y_1^\Delta(\rho(c))) = 0, \end{aligned}$$

and

$$\gamma y(\sigma(d)) + \delta \psi(d)y^\Delta(d) = \gamma \bar{y}(\sigma(d)) + \delta \psi(d)\bar{y}^\Delta(d) - (\gamma x(\sigma(d)) + \delta \psi(d)x^\Delta(d))$$

$$= \gamma \bar{y}(\sigma(d)) + \delta \psi(d) \bar{y}^\Delta(d) - M(\gamma y_1(\sigma(d)) + \delta \psi(d) y_1^\Delta(d)) = 0.$$

Hence,  $y(t)$  is a solution of the boundary value problem (1.1) and (1.2). Hence this completes the proof of the lemma.  $\square$

Let us define a Banach space

$$E = \{y : C[\rho(c), \sigma(d)]_{\mathbb{T}} \rightarrow \mathbb{R}\}$$

endowed with the norm

$$\|y\| = \max\{|y(t)|, t \in [\rho(c), \sigma(d)]_{\mathbb{T}}\}.$$

Define a cone  $K$  on  $E$  by

$$K = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : y(t) \geq q(t)\|y\|, t \in [\rho(c), \sigma(d)]_{\mathbb{T}}\},$$

where  $q(t)$  is defined as in Lemma 2.1. Let us define an operator  $T_\lambda$  on  $K$  by

$$T_\lambda y(t) = \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y(s) - x(s)) + \lambda_2 \bar{h}(s, y(s) - x(s)) + M] \nabla s. \quad (2.10)$$

**Lemma 2.7.** *Assume that  $(H_1)$ – $(H_3)$  hold. Then  $T_\lambda(K) \subset K$  and  $T_\lambda : K \rightarrow K$  is a completely continuous operator.*

*Proof.* First we show that  $T_\lambda(K) \subset K$ . Let  $y \in K$  and  $t \in [\rho(a), \sigma(b)]_{\mathbb{T}}$ . Note that

$$(T_\lambda y)(t) = \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y(s) - x(s)) + \lambda_2 \bar{h}(s, y(s) - x(s)) + M] \nabla s,$$

that is,

$$(T_\lambda y)(t) \leq \int_{\rho(c)}^d \mathcal{G}(s, s) [\lambda_1 \bar{g}(s, y(s) - x(s)) + \lambda_2 \bar{h}(s, y(s) - x(s)) + M] \nabla s.$$

Hence,

$$\|T_\lambda y\| \leq \int_{\rho(c)}^d \mathcal{G}(s, s) [\lambda_1 \bar{g}(s, y(s) - x(s)) + \lambda_2 \bar{h}(s, y(s) - x(s)) + M] \nabla s.$$

By use of the Lemma (2.2), we obtain

$$(T_\lambda y)(t) \geq q(t) \int_{\rho(c)}^d \mathcal{G}(s, s) [\lambda_1 \bar{g}(s, y(s) - x(s)) + \lambda_2 \bar{h}(s, y(s) - x(s)) + M] \nabla s,$$

which implies

$$(T_\lambda y)(t) \geq q(t)\|T_\lambda y\|.$$

Thus,  $T_\lambda(K) \subset K$ . Since  $f$  and  $g$  are continuous, it shows that  $T_\lambda$  is continuous and by the

Arzelà-Ascoli Theorem [14], it is easy to verify that  $T_\lambda$  is a completely continuous operator. Hence this completes the proof of the lemma  $\square$

**Lemma 2.8** ([13]). *Let  $E$  be a real Banach space, and let  $K \subset E$  be a cone. Let  $\Omega_1, \Omega_2$  be two bounded open subsets of  $E$  with  $0 \in \Omega_1, \overline{\Omega_1} \subset \Omega_2$ . Assume that  $T : K \cap (\overline{\Omega_2} \setminus \Omega_1) \rightarrow K$  be a completely continuous operator such that either*

$$\|Ty\| \leq \|y\| \text{ for all } y \in K \cap \partial\Omega_1 \text{ and } \|Ty\| \geq \|y\| \text{ for all } y \in K \cap \partial\Omega_2,$$

or

$$\|Ty\| \geq \|y\| \text{ for all } y \in K \cap \partial\Omega_1 \text{ and } \|Ty\| \leq \|y\| \text{ for all } y \in K \cap \partial\Omega_2,$$

then  $T$  has at least one fixed point in  $K \cap (\overline{\Omega_2} \setminus \Omega_1)$ .

Let us define the following:

$$(L_1) \lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = \infty;$$

$$(L_5) \lim_{y \rightarrow \infty} \frac{h(t, y)}{y} = \infty;$$

$$(L_2) \lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = 0;$$

$$(L_6) \lim_{y \rightarrow \infty} \frac{h(t, y)}{y} = 0;$$

$$(L_3) \lim_{y \rightarrow 0} \frac{g(t, y)}{y} = 0;$$

$$(L_7) \lim_{y \rightarrow 0} \frac{h(t, y)}{y} = 0;$$

$$(L_4) \lim_{y \rightarrow 0} \frac{g(t, y)}{y} = \infty;$$

$$(L_8) \lim_{y \rightarrow 0} \frac{h(t, y)}{y} = \infty.$$

Note that the limits  $(L_i), i \in \mathbb{N}_1^8$ , are assumed to be inform with respect  $t$ .

We would like to establish the existence of solutions for the boundary value problem (1.1) and (1.2) under the following cases:

(I)  $L_1$  and  $L_5$ ;

(VII)  $L_3$  and  $L_5$ ;

(II)  $L_1$  and  $L_6$ ;

(VIII)  $L_3$  and  $L_7$ ;

(III)  $L_1$  and  $L_7$ ;

(IX)  $L_3$  and  $L_8$ ;

(IV)  $L_2$  and  $L_5$ ;

(X)  $L_4$  and  $L_6$ ;

(V)  $L_2$  and  $L_6$ ;

(XI)  $L_4$  and  $L_7$ ;

(VI)  $L_2$  and  $L_8$ ;

(XII)  $L_4$  and  $L_8$ .

**Remark 2.9.** *We fails to apply the Lemma 2.8 for the pairs such as (XIII)  $L_1$  and  $L_8$ , (XIV)  $L_2$  and  $L_7$ , (XV)  $L_3$  and  $L_6$  & (XVI)  $L_4$  and  $L_5$ .*



### 3 Main Results

**Theorem 3.1.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_5)$  hold. Then the boundary value problem (1.1) and (1.2) has a positive solution for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* Let  $\lambda_1$  and  $\lambda_2$  satisfy

$$0 < \lambda_1 + \lambda_2 < \frac{1}{\max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y)}, \tag{3.1}$$

where  $r_1 = \max\{(M + 1)\|y_1\|, r^*, CM\}$ ,  $C$  and  $r^*$  are defined as in Lemma 2.3 and Lemma 2.4, respectively and  $y_1$  be the solution of (1.2) and (2.6). Define  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$ . For  $y \in K \cap \partial\Omega_{r_1}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s)[\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) \int_{\rho(c)}^d \mathcal{G}(t, s) \nabla s + \int_{\rho(c)}^d \mathcal{G}(t, s) M \nabla s \\ &= \left( (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) + M \right) y_1(t) \\ &\leq (1 + M)y_1(t) \\ &\leq r_1 = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_1}. \tag{3.2}$$

Let us choose a constant  $\bar{M} > 0$  such that

$$\frac{1}{2} \bar{M} (\lambda_1 + \lambda_2) \mu \left( \min_{t_1 \leq t \leq t_2} \int_{t_1}^{t_2} \mathcal{G}(t, s) \nabla s \right) \geq 1, \tag{3.3}$$

where

$$\mu = \min_{t_1 \leq s \leq t_2} q(s). \tag{3.4}$$

From  $(L_1)$  and  $(L_5)$ , we have for same  $\bar{M} > 0$  there exists a constant  $l > 0$  such that

$$\begin{aligned} g(t, y) &\geq \bar{M}y \quad \text{for } y \in [l, \infty), \\ h(t, y) &\geq \bar{M}y \quad \text{for } y \in [l, \infty). \end{aligned}$$

Now set  $r_2 = \max\left\{2r_1, 2CM, \frac{2l_1}{\mu}\right\}$ . Define  $\Omega_{r_2} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_2\}$ . For  $y \in$

$K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned}
 y(s) - x(s) &= y(s) - My_1(s) \\
 &\geq y(s) - MCq(s) \\
 &\geq y(s) - \frac{CM}{\|y\|}y(s) \\
 &\geq y(s) - \frac{CM}{r_2}y(s) \\
 &\geq \frac{1}{2}y(s),
 \end{aligned}$$

and

$$\begin{aligned}
 \min_{t_1 \leq s \leq t_2} (y(s) - x(s)) &\geq \min_{t_1 \leq s \leq t_2} \frac{y(s)}{2} \\
 &\geq \min_{t_1 \leq s \leq t_2} \frac{\|y\|}{2} q(s) \\
 &= \frac{r_2\mu}{2} \\
 &\geq l.
 \end{aligned}$$

For  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned}
 \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) (\lambda_1 + \lambda_2) \bar{M} (y(s) - x(s)) \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) (\lambda_1 + \lambda_2) \bar{M} \frac{y(s)}{2} \nabla s \\
 &\geq \frac{1}{2} (\lambda_1 + \lambda_2) \bar{M} \mu \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \|y\| \nabla s \\
 &\geq \|y\|.
 \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_2}. \quad (3.5)$$

By Lemma 2.8,  $T_\lambda$  has a fixed point  $\bar{y}$  with  $r_1 \leq \|\bar{y}\| \leq r_2$ . By use of the Lemma 2.3, it follows

that

$$\begin{aligned} \bar{y}(t) &\geq r_1 q(t) \\ &\geq r_1 \frac{y_1(t)}{C} \\ &\geq M y_1(t) \\ &= x(t). \end{aligned}$$

Hence,  $y = \bar{y} - x$  is a positive solution of the boundary value problem (1.1) and (1.2). This completes the proof of the theorem.  $\square$

**Theorem 3.2.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_4)$  and  $(L_8)$  hold. Then the boundary value problem (1.1) and (1.2) has a positive solution for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* The proof of Theorem 3.2 is similar to that of Theorem 3.1, hence it is omitted.  $\square$

**Theorem 3.3.** *Assume that  $(H_1)$ ,  $(H_2)$ ,  $(L_2)$  and  $(L_6)$  hold. Let there exist two constant  $D > 0$  and  $\eta > 0$  such that*

$$\begin{aligned} g(t, y) &\geq \eta \quad \text{for } t \in [\rho(c), \sigma(d)], y \in [D, \infty), \\ h(t, y) &\geq \eta \quad \text{for } t \in [\rho(c), \sigma(d)], y \in [D, \infty), \end{aligned}$$

*then the boundary value problem (1.1) and (1.2) has a positive solution for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* Set

$$r_1 = \max \left\{ \frac{2D}{\mu}, 2MC \right\}, \tag{3.6}$$

and

$$A = 2r_1 \left( \min_{t_1 \leq t \leq t_2} \int_{t_1}^{t_2} \mathcal{G}(t, s)(\lambda_1 + \lambda_2)\eta \nabla s \right)^{-1}, \tag{3.7}$$

where  $\mu = \min_{t_1 \leq s \leq t_2} q(s)$ . Our claim is that for  $\lambda_i \in [A, \infty), i = 1, 2$ , the boundary value problem (1.1) and (1.2) has a positive solution. Define  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$ . For  $y \in K \cap \partial\Omega_{r_1}$ , we have

$$\begin{aligned} y(s) - x(s) &= y(s) - M y_1(s) \\ &\geq y(s) - MCq(s) \\ &\geq y(s) - \frac{CM}{r_3} y(s) \\ &\geq \frac{1}{2} y(s), \end{aligned}$$

and

$$\begin{aligned}
 \min_{t_1 \leq s \leq t_2} (y(s) - x(s)) &\geq \min_{t_1 \leq s \leq t_2} \frac{y(s)}{2} \\
 &\geq \min_{t_1 \leq s \leq t_2} \frac{\|y\|}{2} q(s) \\
 &= \frac{r_1 \mu}{2} \\
 &\geq D.
 \end{aligned}$$

For  $y \in K \cap \partial\Omega_{r_1}$ , we have

$$\begin{aligned}
 \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) (\lambda_1 + \lambda_2) \eta \nabla s \\
 &= r_1 = \|y\|.
 \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_1}. \quad (3.8)$$

From  $(L_2)$  and  $(L_6)$ , we have

$$\begin{aligned}
 \bar{g}(t, y) &\leq \epsilon y \quad \text{for } t \in [\rho(c), \sigma(d)], y \geq l, \\
 \bar{h}(t, y) &\leq \epsilon y \quad \text{for } t \in [\rho(c), \sigma(d)], y \geq l,
 \end{aligned}$$

On the other hand, by use of the Lemma 2.4, there exists a  $R > 0$  such that

$$R > \max \left\{ 2r_1, \max_{\rho(c) \leq t \leq \sigma(d)} \int_{\rho(c)}^d [\mathcal{G}(t, s) M + 1] \nabla s \right\}.$$

and  $\epsilon$  satisfies

$$\max_{\rho(c) \leq t \leq \sigma(d)} \int_{\rho(c)}^d \mathcal{G}(t, s) [\epsilon \lambda_1 R + \epsilon \lambda_2 R + M] \nabla s \leq R.$$

Let

$$\Omega_R = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < R\}.$$

For  $y \in K \cap \partial\Omega_R$ , we have

$$\begin{aligned} T_\lambda y(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \epsilon R + \epsilon \lambda_2 R + M] \nabla s \\ &\leq R = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for } y \in K \cap \partial\Omega_R. \tag{3.9}$$

By Lemma 2.8,  $T_\lambda$  has a fixed point  $\bar{y}$  with  $r_1 \leq \|\bar{y}\| \leq R$ . It follows that

$$\begin{aligned} \bar{y}(t) &\geq r_1 q(t) \\ &\geq r_1 \frac{y_1(t)}{C} \\ &\geq 2M y_1(t) \\ &\geq x(t). \end{aligned}$$

Hence,  $y = \bar{y} - x$  is a positive solution of the boundary value problem (1.1) and (1.2). This completes the proof of the theorem.  $\square$

**Theorem 3.4.** *Assume that  $(H_1)$ – $(H_3)$ ,  $(L_3)$  and  $(L_7)$  hold. Let there exist two constant  $D > 0$  and  $\eta > 0$  such that*

$$\begin{aligned} g(t, y) &\geq \eta \quad \text{for } t \in [\rho(c), \sigma(d)] y \in [D, l], \\ h(t, y) &\geq \eta \quad \text{for } t \in [\rho(c), \sigma(d)] y \in [D, l], \end{aligned}$$

*then the boundary value problem (1.1) and (1.2) has a positive solution for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* The proof of the Theorem 3.4 is similar to that of Theorem 3.3, hence it is omitted.  $\square$

**Theorem 3.5.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_6)$  hold. Then the boundary value problem (1.1) and (1.2) has at least two positive solutions for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* If  $(L_6)$  holds, then by the Lemma 2.5, there exists a constant  $r_1 > 0$  such that

$$\mathbb{G}(r_1) \leq N r_1.$$

Since  $\lambda_1$  and  $\lambda_2$  are sufficiently small, we have

$$\left[ \lambda_1 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \lambda_2 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \leq r_1.$$

Let  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$ . For  $y \in \partial\Omega_{r_1}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) \left[ \lambda_1 \bar{g}(s, y-x) + \lambda_2 \bar{h}(s, y-x) + M \right] \nabla s \\ &\leq \left( \lambda_1 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \lambda_2 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\ &\quad + \int_{\rho(c)}^d \mathcal{G}(s, s) M \nabla s \leq r_1 = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_{r_1}. \quad (3.10)$$

From  $(L_1)$ , we have

$$g(t, y) > N_1 y \quad \text{for all } y \leq l.$$

Let  $r_2 = \max\left\{2CM, \frac{2l}{\mu}, 2r_1\right\}$  and  $\Omega_{r_2} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_2\}$ . For  $y \in \partial K \cap \Omega_{r_2}$ , we have

$$\begin{aligned} y(s) - x(s) &= y(s) - My_1(s) \\ &\geq y(s) - MCq(s) \\ &\geq y(s) - \frac{CM}{r_5} y(s) \\ &\geq \frac{1}{2} y(s), \end{aligned}$$

and

$$\begin{aligned} \min_{t_1 \leq s \leq t_2} (y(s) - x(s)) &\geq \min_{t_1 \leq s \leq t_2} \frac{y(s)}{2} \\ &\geq \min_{t_1 \leq s \leq t_2} \frac{\|y\|}{2} q(s) \\ &= \frac{r_2 \mu}{2} \\ &\geq l. \end{aligned}$$

For  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned} \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \lambda_1 N_1(y(s) - x(s)) \nabla s \\ &= r_2 = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_{r_2}. \tag{3.11}$$

Let

$$R = \max \left\{ \left( \lambda_1 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} g(t, y) + \lambda_2 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} h(t, y) + M \right) \left( \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \right), 2r_2 \right\},$$

then  $r_1 < r_2 < R$ . Let  $\Omega_R = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < R\}$ . For  $y \in K \cap \Omega_R$ ,  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq \left( \lambda_1 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} g(t, y) + \lambda_2 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} h(t, y) + M \right) \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\ &\leq R = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_R. \tag{3.12}$$

Thus by the Lemma 2.8,  $T_\lambda$  has at least two fixed points. Hence, the boundary value problem (1.1) and (1.2) has at least two positive solutions.  $\square$

**Theorem 3.6.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_2)$  and  $(L_5)$  hold. Then the boundary value problem (1.1) and (1.2) has at least two positive solutions for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* The proof of the Theorem 3.6 is similar to that of Theorem 3.5.  $\square$

**Theorem 3.7.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_4)$  and  $(L_7)$  hold. Then the boundary value problem (1.1) and (1.2) has at least two positive solutions for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* From  $(L_7)$ , we have

$$\lim_{y \rightarrow 0} \frac{h(t, y)}{y} = 0.$$

For  $\epsilon > 0$ , there exists a  $r_1 > 0$  such that

$$h(t, y) \leq \epsilon y \quad \text{for } y \in [0, r_1].$$

Since  $\lambda_1$  and  $\lambda_2$  are sufficiently small, we have

$$\left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \leq r_1.$$

Let  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$ . For  $y \in \partial\Omega_{r_1}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq \int_{\rho(c)}^d \mathcal{G}(s, s) (\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x)) \nabla s + \int_{\rho(c)}^d \mathcal{G}(s, s) M \nabla s \\ &\leq \left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\ &\leq r_1 = \|y\| \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_{r_1}. \quad (3.13)$$

From  $(L_4)$ , we have

$$g(t, y) > N_1 y \quad \text{for all } y \leq l.$$

Let  $r_2 = \max \left\{ 2CM, \frac{2l}{\mu}, 2r_1 \right\}$  and  $\Omega_{r_2} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_2\}$ . For  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned} y(s) - x(s) &= y(s) - My_1(s) \\ &\geq y(s) - MCq(s) \\ &\geq y(s) - \frac{CM}{r_5} y(s) \\ &\geq \frac{1}{2} y(s), \end{aligned}$$



and

$$\begin{aligned} \min_{t_1 \leq s \leq t_2} (y(s) - x(s)) &\geq \min_{t_1 \leq s \leq t_2} \frac{y(s)}{2} \\ &\geq \min_{t_1 \leq s \leq t_2} \frac{\|y\|}{2} q(s) \\ &= \frac{r_2 \mu}{2} \\ &\geq l. \end{aligned}$$

For  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned} \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \lambda_1 N_1(y(s) - x(s)) \nabla s \\ &= r_2 = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_{r_2}. \tag{3.14}$$

Let

$$R = \max \left\{ \left( \lambda_1 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} g(t, y) + \lambda_2 \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} h(t, y) + M \right) \left( \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \right), 2r_2 \right\},$$

then  $r_1 < r_2 < R$ . Let  $\Omega_R = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < R\}$ . For  $y \in K \cap \Omega_R$ ,  $t \in [\rho(c), \sigma(d)]_{\mathbb{T}}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) \left[ \lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M \right] \nabla s \\ &\leq \left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq R}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\ &\leq R = \|y\| \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for all } y \in K \cap \partial\Omega_R. \tag{3.15}$$

Thus by the Lemma 2.8,  $T_\lambda$  has at least two fixed points. Hence, the boundary value problem (1.1) and (1.2) has at least two positive solutions.  $\square$

**Theorem 3.8.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_3)$  and  $(L_8)$  hold. Then the boundary value problem (1.1) and (1.2) has at least two positive solutions for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* The proof of the Theorem 3.8 is similar to that of Theorem 3.5. □

**Theorem 3.9.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_7)$  hold. Then the boundary value problem (1.1) and (1.2) has at least one positive solution for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* From  $(L_1)$ , we have

$$\lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = \infty.$$

For  $k > 0$ , there exists a  $r_1 > 0$  such that

$$g(t, y) \geq ky \quad \text{for } y > r_1.$$

Let  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$  and let  $k$  satisfy

$$\frac{k\mu}{2} \lambda_1 \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \nabla s \geq 1.$$

For  $y \in K \cap \partial\Omega_{r_1}$ , we have

$$\begin{aligned} \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(s, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \lambda_1 k (y - x) \nabla s \\ &\geq \frac{k}{2} \lambda_1 \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \|y\| q(s) \nabla s \\ &\geq \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_1}. \tag{3.16}$$

From  $(L_7)$ , we have

$$\lim_{y \rightarrow 0} \frac{h(t, y)}{y} = 0.$$

For  $\epsilon > 0$ , there exists a  $r_2 > 0$  such that

$$h(t, y) \leq \epsilon y \quad \text{for } y \in [0, \infty).$$

Since  $\lambda_1$  and  $\lambda_2$  are sufficiently small, let

$$\left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} h(t, y) + M \right) \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \leq r_2.$$

Let  $\Omega_{r_2} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_2\}$ . Now for any  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned} (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(t, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq \int_{\rho(c)}^d \mathcal{G}(s, s) [\lambda_1 \bar{g}(t, y - x) + \lambda_2 \bar{h}(s, y - x) + M] \nabla s \\ &\leq \left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\ &\leq r_2 = \|y\|. \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_2}. \tag{3.17}$$

Hence, by the Lemma 2.8,  $T_\lambda$  has a fixed point  $\bar{y}$  with  $r_1 < \|\bar{y}\| < r_2$ . By the Lemma 2.6, the boundary value problem (1.1) and (1.2) has at least one positive solution.  $\square$

**Theorem 3.10.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_3)$  and  $(L_5)$  hold. Then the boundary value problem (1.1) and (1.2) has at least one positive solution for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* The proof of the Theorem 3.10 is similar to that of Theorem 3.9.  $\square$

**Theorem 3.11.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_2)$  and  $(L_8)$  hold. Then the boundary value problem (1.1) and (1.2) has at least one positive solution for  $\lambda_i, i = 1, 2$  are sufficiently small.*

*Proof.* From  $(L_2)$ , we have

$$\lim_{y \rightarrow \infty} \frac{g(t, y)}{y} = 0.$$

By Lemma 2.5, there exist  $r_1 > 0$  and  $k_1 > 0$  such that

$$\mathbb{G}(r_1) \leq k_1 r_1.$$

Let  $\Omega_{r_1} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_1\}$ . Since  $\lambda_1$  and  $\lambda_2$  are sufficiently small, we have

$$\left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_1}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \leq r_1.$$

For any  $y \in K \cap \partial\Omega_{r_1}$ , we obtain

$$\begin{aligned}
 (T_\lambda y)(t) &= \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(t, y-x) + \lambda_2 \bar{h}(s, y-x) + M] \nabla s \\
 &\leq \int_{\rho(c)}^d \mathcal{G}(s, s) [\lambda_1 \bar{g}(t, y-x) + \lambda_2 \bar{h}(s, y-x) + M] \nabla s \\
 &\leq \left[ (\lambda_1 + \lambda_2) \left( \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} g(t, y) + \max_{\substack{\rho(c) \leq t \leq \sigma(d) \\ 0 \leq y \leq r_2}} h(t, y) \right) + M \right] \int_{\rho(c)}^d \mathcal{G}(s, s) \nabla s \\
 &\leq r_1 = \|y\|.
 \end{aligned}$$

Thus,

$$\|T_\lambda y\| \leq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_1}. \quad (3.18)$$

From  $(L_8)$ , we have

$$\lim_{y \rightarrow 0} \frac{h(t, y)}{y} = \infty.$$

For  $k > 0$ , there exists a  $l > 0$  such that

$$h(t, y) \geq ky \quad \text{for } y \in [0, l].$$

Let  $r_2 = \left\{ 2cm, \frac{2l}{\mu}, 2r_1 \right\}$  and  $\Omega_{r_2} = \{y \in C[\rho(c), \sigma(d)]_{\mathbb{T}} : \|y\| < r_2\}$ . For any  $y \in K \cap \partial\Omega_{r_2}$ , we have

$$\begin{aligned}
 \min_{t \in [t_1, t_2]} (T_\lambda y)(t) &= \min_{t \in [t_1, t_2]} \int_{\rho(c)}^d \mathcal{G}(t, s) [\lambda_1 \bar{g}(t, y-x) + \lambda_2 \bar{h}(s, y-x) + M] \nabla s \\
 &\geq \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \lambda_2 k (y(s) - x(s)) \nabla s \\
 &\geq \frac{k}{2} \lambda_2 \mu \min_{t \in [t_1, t_2]} \int_{t_1}^{t_2} \mathcal{G}(t, s) \|y\| \nabla s \\
 &\geq r_2 = \|y\|.
 \end{aligned}$$

Thus,

$$\|T_\lambda y\| \geq \|y\| \quad \text{for } y \in K \cap \partial\Omega_{r_2}. \quad (3.19)$$

Hence, by the Lemma 2.8,  $T_\lambda$  has a fixed point  $\bar{y}$  with  $r_1 < \|\bar{y}\| < r_2$ . By the Lemma 2.6, the boundary value problem (1.1) and (1.2) has at least one positive solution.  $\square$

**Theorem 3.12.** *Let  $(H_1)$ – $(H_3)$ ,  $(L_4)$  and  $(L_6)$  hold. Then the boundary value problem (1.1) and (1.2) has at least one positive solution for  $\lambda_i$ ,  $i = 1, 2$  are sufficiently small.*

*Proof.* The proof of the Theorem 3.12 is similar to that of Theorem 3.11.  $\square$

## 4 Examples

We shall illustrate few examples in different time scales to justify the results obtained in the preceding section.

**Example 4.1.** Let us consider the following boundary value problem on time scale  $\mathbb{T} = \mathbb{R}$ ,

$$((1 + t^2)y')' + \frac{1}{2} \frac{1 + y^2}{52} + \frac{1}{4} \frac{y^2 \sin^2 y}{35} = 0, \quad t \in [0, 1], \tag{4.1}$$

with boundary conditions

$$\begin{aligned} y(0) - y'(0) &= 0, \\ y(1) + 2y'(1) &= 0, \end{aligned} \tag{4.2}$$

where  $\psi(t) = 1 + t^2$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = \frac{1+y^2}{52}$  and  $h(t, y) = \frac{y^2 \sin^2 y}{35}$ . Green's function for the boundary value problem (4.1) and (4.2) is given by

$$\mathcal{G}(t, s) = \frac{1}{2 + \frac{\pi}{4}} \begin{cases} \left(1 + \tan^{-1} t\right) \left(1 + \frac{\pi}{4} - \tan^{-1} s\right), & t \leq s, \\ \left(1 + \tan^{-1} s\right) \left(1 + \frac{\pi}{4} - \tan^{-1} t\right), & s \leq t. \end{cases}$$

All the conditions  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_5)$  are satisfied for  $(t, y) \in [0, 1] \times [0, 100]$ . By Theorem 3.1, boundary value problem (4.1) and (4.2) has at least one positive solution for  $\lambda_1 = \frac{1}{2}$  and  $\lambda_2 = \frac{1}{4}$ .

**Example 4.2.** Let us consider the following boundary value problem on time scale  $\mathbb{T} = \mathbb{Z}$ ,

$$\nabla((1 + t)^{-1}y^\Delta) + \lambda_1 \sin^2 y + \lambda_2 \sqrt{y} \cos y = 0, \quad t \in [0, 3], \tag{4.3}$$

with boundary conditions

$$\begin{aligned} y(0) - \Delta y(0) &= 0, \\ y(3) + \frac{1}{3} \Delta y(2) &= 0, \end{aligned} \tag{4.4}$$

where  $\psi(t) = (1 + t)^{-1}$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = \sin^2 y$  and  $h(t, y) = \sqrt{y} \cos y$ . Green's function for the boundary value problem (4.3) and (4.4) is given by

$$\mathcal{G}(t, s) = \frac{1}{11} \begin{cases} \left(1 + \frac{t^2 + 3t}{2}\right) \left(1 + \frac{(3-s)(s+6)}{2}\right), & t \leq s, \\ \left(1 + \frac{s^2 + 3s}{2}\right) \left(1 + \frac{(3-t)(t+6)}{2}\right), & s \leq t. \end{cases}$$

All the conditions  $(H_1)$ – $(H_3)$ ,  $(L_2)$  and  $(L_6)$  are satisfied for  $(t, y) \in [0, 3] \times [0, 100]$ . Let  $D = 1$

and  $\eta = \frac{1}{2}$  such that  $g(t, y) \geq \frac{1}{2}$  and  $h(t, y) \geq \frac{1}{2}$  for  $t \in [0, 3]$ ,  $y \in [1, \infty)$ . By Theorem 3.3, boundary value problem (4.3) and (4.4) has at least one positive solution for  $\lambda_i$ ;  $i = 1, 2$  are sufficiently small.

**Example 4.3.** Consider the boundary value problem on time scale  $\mathbb{T} = q^{\mathbb{Z}} = \{2^k : k \in \mathbb{Z}\} \cup \{0\}$ , where  $q = 2 > 1$ ,

$$D^q \left( (1+t)^{-1} D_q y(t) \right) + \lambda_1 \frac{y^2}{\sin y} + \lambda_2 \ln(y) = 0, \quad t \in [0, 2], \quad (4.5)$$

with boundary conditions

$$\begin{aligned} y(0) - D_q y(0) &= 0, \\ y(2) + \frac{1}{2} D_q y(1) &= 0, \end{aligned} \quad (4.6)$$

where  $\psi(t) = (1+t)^{-1}$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = \frac{y^2}{\sin y}$  and  $h(t, y) = \ln(y)$ . Green's function for the boundary value problem (4.5) and (4.6) is given by

$$\mathcal{G}(t, s) = \frac{3}{20} \begin{cases} \left( \frac{2t^2+3t+3}{3} \right) \left( \frac{17-3s-2s^2}{3} \right), & t \leq s, \\ \left( \frac{2s^2+3s+3}{3} \right) \left( \frac{17-3t-2t^2}{3} \right), & s \leq t. \end{cases}$$

The conditions  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_6)$  are satisfied for  $(t, y) \in [0, 2] \times [0, 100]$ . By Theorem 3.5, boundary value problem (4.5) and (4.6) has at least two positive solutions for  $\lambda_i$ ;  $i = 1, 2$  are sufficiently small.

**Example 4.4.** Let us consider the time scale  $\mathbb{T} = \mathbb{P}_{a,b} = \bigcup_{k=0}^{\infty} [k(a+b), k(a+b)+a] = \mathbb{P}_{1,1} = \bigcup_{k=0}^{\infty} [2k, 2k+1]$ , where  $a = b = 1$ . Consider the following boundary value problem:

$$\begin{cases} y^{\Delta \nabla} + \lambda_1 \sqrt{y} + \lambda_2 y \ln(1+y), & t \in (0, 2), \\ y(0) = 0, \quad y(2) = 0, \end{cases} \quad (4.7)$$

where  $\psi(t) = 1$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = \sqrt{y}$  and  $h(t, y) = y \ln(y)$ . Green's function for the boundary value problem (4.7) is given by

$$\mathcal{G}(t, s) = \frac{1}{2} \begin{cases} t(1-s), & t \leq s, \\ (1+s)(2-t), & s \leq t. \end{cases}$$

The conditions  $(H_1)$ – $(H_3)$ ,  $(L_4)$  and  $(L_7)$  are satisfied for  $(t, y) \in [0, 2] \times [0, 100]$ . By Theorem 3.7, boundary value problem (4.7) has at least two positive solutions for  $\lambda_i$ ;  $i = 1, 2$  are sufficiently small.

**Example 4.5.** Consider the boundary value problem on time scale  $\mathbb{T} = \{\frac{n}{2} : t \in \mathbb{N}_0\}$ :

$$y^{\Delta \nabla}(t) + \lambda_1 y \ln(1 + y) + \lambda_2 \frac{\sqrt{y} \sin y}{6} = 0, \quad t \in \left[0, \frac{3}{2}\right], \tag{4.8}$$

with boundary conditions

$$\begin{aligned} y(0) - y^\Delta(0) &= 0, \\ y\left(\frac{3}{2}\right) + y^\Delta(1) &= 0, \end{aligned} \tag{4.9}$$

where  $\psi(t) = 1$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = y \ln(1 + y)$  and  $h(t, y) = \frac{\sqrt{y} \sin y}{6}$ . Green's function for the boundary value problem (4.8) and (4.9) is given by

$$\mathcal{G}(t, s) = \frac{2}{7} \begin{cases} (1 + s) \left(\frac{5}{2} - t\right), & t \leq s, \\ (1 + t) \left(\frac{5}{2} - s\right), & s \leq t. \end{cases}$$

The conditions  $(H_1)$ – $(H_3)$ ,  $(L_1)$  and  $(L_7)$  are satisfied for  $(t, y) \in [0, \frac{3}{2}] \times [0, 100]$ . By Theorem 3.9, boundary value problem (4.8) and (4.9) has at least one positive solutions for  $\lambda_i$ ;  $i = 1, 2$  are sufficiently small.

**Example 4.6.** Consider the following boundary value problem in time scale  $\mathbb{T} = h\mathbb{Z} = \{hk : k \in \mathbb{Z}\}$ , where  $h = \frac{1}{2} > 0$ ,

$$\left((1 + t)^{-1} y^\Delta\right)^\nabla + \lambda_1 \sqrt{y} \sin y + \lambda_2 = 0 \quad \text{for } t \in [0, 2], \tag{4.10}$$

with boundary conditions

$$\begin{aligned} y(0) - y^\Delta(0) &= 0, \\ y(2) + \frac{2}{5} y^\Delta\left(\frac{3}{2}\right) &= 0, \end{aligned} \tag{4.11}$$

where  $\psi(t) = (1 + t)^{-1}$ ,  $M = 1$ ,  $\alpha, \beta, \gamma, \delta \geq 0$ ,  $g(t, y) = \sqrt{y} \sin y$  and  $h(t, y) = 1$ . Green's function for the boundary value problem (4.10) and (4.11) is given by

$$\mathcal{G}(t, s) = \frac{2}{13} \begin{cases} \left(1 + \frac{s(2s+5)}{4}\right) \left(1 + \frac{(2-t)(2t+9)}{4}\right), & s \leq t, \\ \left(1 + \frac{t(2t+5)}{4}\right) \left(1 + \frac{(2-s)(2s+9)}{4}\right), & t \leq s. \end{cases}$$

The conditions  $(H_1)$ – $(H_3)$ ,  $(L_2)$  and  $(L_8)$  are satisfied for  $(t, y) \in [0, 2] \times [0, 100]$ . By Theorem 3.11, boundary value problem (4.10) and (4.11) has at least one positive solutions for  $\lambda_i$ ;  $i = 1, 2$  are sufficiently small.

## References

- [1] D. R. Anderson and P. J. Y. Wong, “Positive solutions for second-order semipositone problems on time scales”, *Comput. Math. Appl.*, vol. 58, no. 2, pp. 281–291, 2009.
- [2] D. R. Anderson and C. Zhai, “Positive solutions to semi-positone second-order three-point problems on time scale”, *Appl. Math. Comput.*, vol. 215, no. 10, pp. 3713–3720, 2010.
- [3] R. Aris, *Introduction to the analysis of chemical reactors*, New Jersey: Prentice Hall, Englewood Cliffs, 1965.
- [4] D. Bai, and Y. Xu, “Positive solutions for semipositone BVPs of second-order difference equations”, *Indian J. Pure Appl. Math.*, vol. 39, no.1, pp. 59–68, 2008.
- [5] M. Bohner and A. Peterson, *Dynamic Equations on Time Scales: An Introduction with Applications*, Boston: Birkhäuser, 2001.
- [6] M. Bohner and A. Peterson, *Advances in Dynamic Equations on Time Scales*, Boston: Birkhäuser, 2003.
- [7] R. Dahal, “Positive solutions for a second-order, singular semipositone dynamic boundary value problem”, *Int. J. Dyn. Syst. Differ. Equ.*, vol. 3, no. 1–2, pp. 178–188, 2011.
- [8] L. Erbe and A. Peterson, “Positive solutions for a nonlinear differential equations on a measure chain”, *Math. Comput. Modelling*, vol. 32, no. 5–6, pp. 571–585, 2000.
- [9] C. Giorgi and E. Vuk, “Steady-state solutions for a suspension bridge with intermediate supports”, *Bound. Value Probl.*, Paper No. 204, 17 pages, 2013.
- [10] C. S. Goodrich, “Existence of a positive solution to a nonlocal semipositone boundary value problem on a time scale”, *Comment. Math. Univ. Carolin.*, vol. 54, no. 4, pp. 509–525, 2013.
- [11] S. Hilger, “Analysis on measure chains—a unified approach to continuous and discrete calculus”, *Results Math.*, vol. 18, no. 1–2, pp. 18–56, 1990.
- [12] G. Infante, P. Pietramala and M. Tenuta, “Existence and localization of positive solutions for a nonlocal BVP arising in chemical reactor theory”, *Commun. Nonlinear Sci. Numer. Simul.*, vol. 19, no 7, pp. 2245–2251, 2014.
- [13] M. A. Krasnosel’skii, *Positive Solutions of Operator Equations*, Groningen: P. Noordhoff, 1964.
- [14] E. Kreyszig, *Introductory Functional Analysis With Applications*, New York: John Wiley & Sons, Inc., 1978.



- 
- [15] J. Selgrade, “Using stocking and harvesting to reverse period-doubling bifurcations in models in population biology”, *J. Differ. Equations Appl.*, vol. 4, no. 2, pp. 163–183, 1998.
- [16] J. P. Sun and W. T. Li, “Existence of positive solutions to semipositone Dirichlet BVPs on time scales”, *Dynam. Systems Appl.*, vol. 16, no. 3, pp. 571–578, 2007.
- [17] Y. Yang and F. Meng, “Positive solutions of the singular semipositone boundary value problem on time scales”, *Math. Comput. Modelling*, vol. 52, no. 3–4, pp. 481–489,