

Investigating the existence and multiplicity of solutions to $\varphi(x)$ -Kirchhoff problem

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ABSTRACT

In this article, we want to discuss variational methods such as the Mountain pass theorem and the Symmetric Mountain pass theorem, without the Ambrosetti-Rabinowitz condition. We prove the existence and multiplicity of nontrivial weak solutions for the problem of the following form

$$\begin{cases} -\left(\alpha-\beta\int_{\Omega}\frac{1}{\varphi(x)}|\nabla v|^{\varphi(x)}dx\right)\Delta_{\varphi(x)}v+|v|^{\psi(x)-2}v\\ &=\lambda\eta(x,v),\\ &x\in\Omega,\\ \left(\alpha-\beta\int_{\partial\Omega}\frac{1}{\varphi(x)}|\nabla v|^{\varphi(x)}dx\right)|\nabla v|^{\varphi(x)-2}\frac{\partial v}{\partial\nu}=0\\ &x\in\partial\Omega, \end{cases}$$

where $\alpha \geq \beta > 0$, $\Delta_{\varphi(x)}v$ is the $\varphi(x)$ -Laplacian operator, Ω is a smooth bounded domain in \mathbb{R}^N with smooth boundary $\partial\Omega$ and ν is the outer unit normal to $\partial\Omega$, $\varphi(x), \psi(x) \in C(\bar{\Omega})$ with $1 < \varphi(x) < N$, $\varphi(x) < \psi(x) < \varphi^*(x) := \frac{N\varphi(x)}{N - \varphi(x)}$, $\lambda > 0$ is a real parameter and $\eta(x,t) \in C(\bar{\Omega} \times \mathbb{R}, \mathbb{R})$.





RESUMEN

En este artículo discutimos métodos variacionales, como el teorema del paso de la montaña y el teorema simétrico del paso de la montaña, sin la condición de Ambrosetti-Rabinowitz. Demostramos la existencia y multiplicidad de soluciones débiles no triviales para el problema de la siguiente forma

$$\begin{cases} -\left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) \Delta_{\varphi(x)} v + |v|^{\psi(x) - 2} v \\ = \lambda \eta(x, v), \\ x \in \Omega, \\ \left(\alpha - \beta \int_{\partial \Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) |\nabla v|^{\varphi(x) - 2} \frac{\partial v}{\partial \nu} = 0 \\ x \in \partial \Omega, \end{cases}$$

donde $\alpha \geq \beta > 0$, $\Delta_{\varphi(x)}v$ es el $\varphi(x)$ operador Laplaciano, Ω es un dominio acotado y suave en \mathbb{R}^N con borde suave $\partial\Omega$ y ν es la normal unitaria exterior a $\partial\Omega$, $\varphi(x), \psi(x) \in C(\bar{\Omega})$ con $1 < \varphi(x) < N, \ \varphi(x) < \psi(x) < \varphi^*(x) := \frac{N\varphi(x)}{N - \varphi(x)}, \ \lambda > 0$ es un parámetro real y $\eta(x,t) \in C(\bar{\Omega} \times \mathbb{R}, \mathbb{R})$.

Keywords and Phrases: Generalized Lebesgue-Sobolev spaces, weak solutions, mountain pass theorem, symmetric mountain pass theorem.



1 Introduction

In this article, we consider the following problem

$$\begin{cases}
-\left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) \Delta_{\varphi(x)} v + |v|^{\psi(x) - 2} v = \lambda \eta(x, v), & x \in \Omega, \\
\left(\alpha - \beta \int_{\partial\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) |\nabla v|^{\varphi(x) - 2} \frac{\partial v}{\partial \nu} = 0, & x \in \partial\Omega,
\end{cases}$$
(1.1)

where $\alpha \geq \beta > 0$, $\Delta_{\varphi(x)} v$ is the $\varphi(x)$ -Laplacian operator, defined as $\Delta_{\varphi(x)} v := \operatorname{div}(|\nabla v|^{\varphi(x)-2} \nabla v) = \sum_{i=1}^{N} \left(|\nabla v|^{\varphi(x)-2} \frac{\partial v}{\partial x_i} \right)$, Ω is a smooth bounded domain in \mathbb{R}^N with smooth boundary $\partial \Omega$ and ν is the outer unit normal to $\partial \Omega$ and $\varphi(x), \psi(x) \in C(\bar{\Omega})$ with $1 < \varphi(x) < N$, $\varphi(x) < \psi(x) < \varphi^*(x) := \frac{N\varphi(x)}{N-\varphi(x)}$, $\lambda > 0$ is a real parameter. We define φ_i and φ_s for convenience as follows: $\varphi_i := \inf_{\Omega} \varphi(x)$ and $\varphi_s := \sup_{\Omega} \varphi(x)$, for all $\varphi(x) \in C(\bar{\Omega})$. The function $\eta(x,t) \in C(\bar{\Omega} \times \mathbb{R}, \mathbb{R})$ satisfies:

$$|\eta(x,t)| \leq c(1+|t|^{r(x)-1}), \forall (x,t) \in \Omega \times \mathbb{R}, \text{ where } c>0 \text{ and } \varphi(x) < r(x) < \varphi^*(x),$$

$$(\eta_2)$$
 $\lim_{t\to 0} \frac{\eta(x,t)}{|t|^{\varphi(x)-2}t} = 0$, uniformly a.e. $x \in \Omega$,

$$(\eta_3)$$
 $\lim_{|t|\to\infty} \frac{\eta(x,t)}{|t|^{\varphi_s}} = +\infty$, uniformly a.e. $x \in \Omega$,

 (η_4) there exists a constant $c_0 > 0$ such that $\hat{H}(x,t) \leq \hat{H}(x,s) + c_0$ for each $x \in \Omega$, 0 < |t| < s, where $\hat{H}(x,t) := t \eta(x,t) - \varphi_s H(x,t)$ and $H(x,t) := \int_0^t \eta(x,s) ds$,

$$(\eta_5)$$
 $\eta(x,-t) = -\eta(x,t)$ for all $(x,t) \in \Omega \times \mathbb{R}$.

In addition to the conditions given for η , the functions $\varphi(x), \psi(x), r(x)$ must satisfy the following condition, which we call the $(\varphi \psi r)$ -condition:

$$1 < \varphi_i < \varphi(x) < \varphi_s < \psi_i < \psi(x) < \psi_s < 2\varphi_i < r_i < r(x) < r_s < \varphi^*(x).$$

Sobolev spaces are essential in contemporary analysis, especially in the study of partial differential equations (PDEs) and functional analysis. These spaces generalize the classical concepts of differentiability and integrability, offering a more adaptable structure for analyzing functions whose derivatives might not be classically well-defined. By incorporating weak derivatives, Sobolev spaces allow for the examination of broader issues in areas such as mathematical physics, fluid dynamics, and engineering applications, see [1,4,5,7–9,12,20,21,26,27,32,34,38].

The necessity of Sobolev spaces arises from their ability to handle irregularities and discontinuities in functions that appear naturally in real-world problems. For instance, solutions to PDEs often lack classical differentiability but possess weak derivatives that allow their analysis within Sobolev



spaces. This makes them indispensable in addressing variational problems and boundary value problems.

Kirchhoff's problems, named after the German physicist Gustav Kirchhoff [28], are fundamental in the study of mechanics and mathematical physics, particularly in understanding wave propagation and elasticity theory. Kirchhoff's equations describe the motion of elastic surfaces and play a key role in modeling vibrating systems, such as strings, membranes, and plates. Recent research in this field has focused on nonlinear versions of Kirchhoff's equations, particularly in higher dimensions, where the complexity of the problem increases, see [2,6,10,11,14,17–19,24,25,31,34,37].

Variational methods have a relatively long history. Many scientists have studied in this field and have achieved many successes. Due to the applicability of this method in experimental sciences, it has always been of interest [?,3,8,13,15,16,22,23,26,29,33,35,36]. In these methods, especially those used to solve boundary value problems, the Palais-Smale condition ((PS)-condition in short) plays a crucial role in ensuring the existence of critical points, which correspond to solutions of the problem. This condition provides a framework for the analysis of functionals in infinite-dimensional spaces, such as Sobolev spaces. On the other hand, the Cerami condition ((C)-condition in short) is a variation of the (PS)-condition that is particularly useful in dealing with problems where the (PS)-condition might not hold. This modified condition is often more applicable in certain classes of problems, particularly those involving non-compact domains or complex geometries.

Now we state our main results.

Theorem 1.1. Suppose $(\eta_1) - (\eta_4)$ and the $(\varphi \psi r)$ -condition hold. Then problem (1.1) has at least a nontrivial weak solution for all $\lambda < \lambda_0$ (λ_0 which has been given in Section 3).

Theorem 1.2. Suppose $(\eta_1), (\eta_2), (\eta_4), (\eta_5)$ and the $(\varphi \psi r)$ -condition hold. Then problem (1.1) has infinitely many weak solutions for all $\lambda < \lambda_0$ (λ_0 which has been given in Section 3).

To prove our results, we will use inequalities and applied theorems such as Hölder and Poincaré inequalities and the embedding, Mountain pass and Symmetric Mountain pass theorems.

2 Preliminary results

In this section, we recall some important definitions and essential characteristics of the generalized Lebesgue-Sobolev spaces $L^{\varphi(x)}(\Omega)$ and $W^{1,\varphi(x)}(\Omega)$ where $\Omega \subset \mathbb{R}^N$ is an open set. In this regard, we refer readers to the book of Musielak [32] and the papers [20, 21]. Set

$$C_{+}(\bar{\Omega}) := \{ h : h \in C(\bar{\Omega}), h(x) > 1 \text{ for all } x \in \bar{\Omega} \},$$

and for each $\varphi(x) \in C_+(\bar{\Omega})$



$$L^{\varphi(x)}(\Omega) = \left\{ \upsilon : \text{a measurable real-valued function such that } \int_{\Omega} |\upsilon(x)|^{\varphi(x)} \, dx < \infty \right\},$$

is the definition of variable exponent Lebesgue space, that by mentioned the following norm (socalled Luxemburg norm) is reflexive and separable Banach space

$$\|v\|_{\varphi(x)} := \inf \left\{ \mu > 0; \int_{\Omega} \left| \frac{v(x)}{\mu} \right|^{\varphi(x)} dx \le 1 \right\}.$$

These spaces are similar to classical Lebesgue spaces in many aspects [35]:

a) If $0 < |\Omega| < \infty$ and $\varphi_1(x), \varphi_2(x)$ are variable exponents so that $\varphi_1(x) \le \varphi_2(x)$ a.e. $x \in \Omega$, then there is a continuous embedding

$$L^{\varphi_2(x)}(\Omega) \hookrightarrow L^{\varphi_1(x)}(\Omega).$$

b) The Hölder inequality holds, i.e., if $L^{\varphi'(x)}(\Omega)$ is a conjugate of $L^{\varphi(x)}(\Omega)$, where $\frac{1}{\varphi(x)} + \frac{1}{\varphi'(x)} = 1$, we have

$$\left| \int_{\Omega} uv \, dx \right| \leq \left(\frac{1}{\varphi_l} + \frac{1}{\varphi_l'} \right) \|u\|_{\varphi(x)} \|v\|_{\varphi'(x)}, \quad \forall u \in L^{\varphi(x)}(\Omega), \quad \forall v \in L^{\varphi'(x)}(\Omega).$$

The modular plays an essential role in manipulating the $L^{\varphi(x)}$ spaces and is defined by the following relation, $\rho_{\varphi(x)}: L^{\varphi(x)} \to \mathbb{R}$;

$$\rho_{\varphi(x)}(v) = \int_{\Omega} |v|^{\varphi(x)} dx.$$

Proposition 2.1 ([20]). If $v, v_n \in L^{\varphi(x)}(\Omega)$ and $\varphi_s < +\infty$, then the following relations hold

- $(1) \|v\|_{\varphi(x)} > 1 \implies \|v\|_{\varphi(x)}^{\varphi_l} \le \rho_{\varphi(x)}(v) \le \|v\|_{\varphi(x)}^{\varphi_s};$
- (2) $||v||_{\varphi(x)} < 1 \implies ||v||_{\varphi(x)}^{\varphi_s} \le \rho_{\varphi(x)}(v) \le ||v||_{\varphi(x)}^{\varphi_t};$
- (3) $||v||_{\varphi(x)} < 1$ (respectively, = 1; > 1) $\iff \rho_{\varphi(x)}(v) < 1$ (respectively, = 1; > 1);
- $(4) \ \|v_n\|_{\varphi(x)} \to 0 \quad (respectively, \to +\infty) \iff \rho_{\varphi(x)}(v) = 0 \quad (respectively, \to +\infty);$
- (5) $\lim_{n \to \infty} \|v_n v\|_{\varphi(x)} = 0 \iff \lim_{n \to \infty} \rho_{\varphi(x)}(v_n v) = 0;$
- (6) For $v \neq 0$, $||v||_{\varphi(x)} = \lambda \iff \rho\left(\frac{v}{\lambda}\right) = 1$.

Definition 2.2 ([21]). If $\Omega \subset \mathbb{R}^N$, the Sobolev space with variable exponent $W^{1,\varphi(x)}(\Omega)$ is defined as

$$W^{1,\varphi(x)}(\Omega) := \{ \upsilon : \Omega \to \mathbb{R} : \upsilon \in L^{\varphi(x)}(\Omega), \, |\nabla \upsilon| \in L^{\varphi(x)}(\Omega) \},$$



endowed with the following norm

$$||v||_{W^{1,\varphi(x)}} := |||v||| = ||v||_{\varphi(x)} + ||\nabla v||_{\varphi(x)},$$

or equivalently

$$|||v||| = \inf \left\{ \mu > 0, \int_{\Omega} \frac{\|\nabla v(x)\|_{\varphi(x)}^{\varphi(x)} + \|v\|_{\varphi(x)}^{\varphi(x)}}{\mu^{\varphi(x)}} dx \le 1 \right\}.$$

Proposition 2.3 ([20]). The Poincaré inequality in $W^{1,\varphi(x)}(\Omega)$ holds, that is, there exists a positive constant c so that

$$\|v\|_{\varphi(x)} \le c \|\nabla v\|_{\varphi(x)}, \quad \forall v \in W^{1,\varphi(x)}(\Omega).$$
 (2.1)

Proposition 2.4 (Sobolev embedding [21]). If $\varphi(x), \psi(x) \in C_+(\bar{\Omega})$ and $1 \leq \psi(x) \leq \varphi^*(x)$ for each $x \in \bar{\Omega}$, then there exists a continuous embedding

$$W^{1,\varphi(x)}(\Omega) \hookrightarrow L^{\psi(x)}(\Omega).$$
 (2.2)

If $1 < \psi(x) < \varphi^*(x)$, the continuous embedding is compact.

In the sequel, the constant c_{emb} represents the Sobolev embedding quantity, and we denote by $X := W^{1,\varphi(x)}(\Omega); X^* = (W^{1,\varphi(x)}(\Omega))^*$, the dual space and $\langle \cdot, \cdot \rangle$, the dual pair.

Lemma 2.5 ([21]). Suppose

$$J(\upsilon) = \int_{\Omega} \frac{1}{\varphi(x)} |\nabla \upsilon|^{\varphi(x)} \, dx, \quad \forall \upsilon \in X,$$

then $J(v) \in C^1(X,\mathbb{R})$ and the derivative operator J' of J is

$$\langle J'(v), \vartheta \rangle = \int_{\Omega} |\nabla v|^{\varphi(x)-2} \nabla v \nabla \vartheta \, dx, \quad \forall v, \vartheta \in X$$

and the following relations hold:

- (1) J is a convex functional,
- (2) $J': X \to X^*$ is a strictly monotone operator and bounded homeomorphism,
- (3) J' is a mapping of type (S_+) , it means, $v_n \rightharpoonup v$ (weakly) and $\lim_{n \to +\infty} \sup \langle J'(v), v_n v \rangle \leq 0$, imply $v_n \to v$ (strongly) in $W_0^{1,\varphi(x)}(\Omega)$.



Definition 2.6. $v \in X$ is a weak solution of problem (1.1), if

$$\left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) \int_{\Omega} |\nabla v|^{\varphi(x) - 2} \nabla v \nabla v dx + \int_{\Omega} |v|^{\psi(x) - 2} v \nu dx = \lambda \int_{\Omega} \eta(x, v) \nu dx,$$

$$\forall \nu \in X.$$

The energy functional related to our problem, $J_{\lambda}: X \to \mathbb{R}$ such that

$$J_{\lambda}(v) = \alpha \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx - \frac{\beta}{2} \left(\int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx \right)^{2} + \int_{\Omega} \frac{1}{\psi(x)} |v|^{\psi(x)} dx - \lambda \int_{\Omega} H(x, v) dx, \quad \forall v \in X, \quad (2.3)$$

which is also well defined and of class C^1 in (X, \mathbb{R}) .

Now we define J'_{λ} as the derivative operator of J_{λ} in the weak sense, by the following formula,

$$\langle J_{\lambda}'(v), \nu \rangle = \left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} dx\right) \int_{\Omega} |\nabla v|^{\varphi(x)-2} \nabla v \nabla v dx + \int_{\Omega} |v|^{\psi(x)-2} v \nu dx - \lambda \int_{\Omega} \eta(x, v) \nu dx, \quad \forall v, \nu \in X. \quad (2.4)$$

A critical point of J_{λ} is clearly a weak solution of problem (1.1).

Definition 2.7. If $(X, \|\cdot\|)$ is a real Banach space and $J \in C^1(X, \mathbb{R})$, then we can say that J ensures Cerami-condition in level c ($(C)_c$ -condition in short), if for all sequence $\{v_n\} \subset X$ satisfying

$$J(v_n) \to c \quad and \quad ||J'(v_n)||_{X^*} (1 + ||v_n||_X) \to 0,$$
 (2.5)

then, $\{v_n\}$ contains a convergent subsequence.

If this condition holds for each $c \in \mathbb{R}$, it can be called (C)-condition.

3 Proof of Theorem 1.1

To prove Theorem 1.1, we will use the following Mountain pass theorem.

Theorem 3.1 (Mountain pass theorem [8]). Let X be a real Banach space, let $J_{\lambda}: X \to \mathbb{R}$ as $J_{\lambda} \in C^1(X,\mathbb{R})$ that ensures the $(C)_c$ -condition and $J_{\lambda}(0) = 0$, such that

- (a) there exists R > 0 and $\alpha > 0$, so that $J_{\lambda}(v) \geq \alpha$ for each $v \in X$ with |||v||| = R,
- (b) there is a function $e \in X$ such that |||e||| > R and $J_{\lambda}(e) \leq 0$.

So, J_{λ} has a critical value $c \geq \alpha$, that is $v \in X$, such that $J_{\lambda}(v) = c$ and $J'_{\lambda}(v) = 0$ in X^* .



First, we prove that J_{λ} has the geometry of the above Mountain pass theorem.

Lemma 3.2. (a) Under the condition (η_3) the functional J_{λ} is unbounded from below.

(b) Under the conditions (η_1) and (η_2) , v = 0 is a strict local minimum for J_{λ} .

Proof. (a) By (η_3) , we have

$$\forall M > 0, \ \exists c_M > 0; \quad \eta(x, t) \ge M|t|^{\varphi_s} - c_M, \quad \forall x \in \Omega, \quad t \in \mathbb{R}.$$
 (3.1)

If $v \in X$ for v > 0, and (3.1), we have

$$\begin{split} J_{\lambda}(tv) &= \alpha \int_{\Omega} \frac{t^{\varphi(x)}}{\varphi(x)} |\nabla v|^{\varphi(x)} \, dx - \frac{\beta}{2} \left(\int_{\Omega} \frac{t^{\varphi(x)}}{\varphi(x)} |\nabla v|^{\varphi(x)} \, dx \right)^{2} + \int_{\Omega} \frac{t^{\psi(x)}}{\psi(x)} |v|^{\psi(x)} \, dx \\ &- \lambda \int_{\Omega} H(x, tv) \, dx \\ &\leq \alpha t^{\varphi_{s}} \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} \, dx - \frac{\beta}{2} t^{2\varphi_{l}} \left(\int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} \, dx \right)^{2} + t^{\psi_{s}} \int_{\Omega} \frac{1}{\psi(x)} |v|^{\psi(x)} \, dx \\ &- M \lambda t^{\varphi_{s}} \int_{\Omega} |v|^{\varphi(x)} \, dx + \lambda c_{M} |\Omega| \to -\infty, \quad \text{as} \quad t \to +\infty, \end{split}$$

since $\varphi_s < \psi_s < 2\varphi_l$, thus, J_λ is unbounded from below.

(b) According to the conditions (η_1) and (η_2) , we have

$$\forall \varepsilon > 0, \ \exists c_{\varepsilon} > 0; \quad H(x,t) \le \varepsilon |t|^{\varphi(x)} + c_{\varepsilon} |t|^{r(x)}, \quad \forall (x,t) \in \Omega \times \mathbb{R}.$$

Therefore, if $v \in X$ with $|||v||| \le 1$, by Poincaré inequality and Sobolev embedding (2.2), we have

$$\begin{split} J_{\lambda}(v) &= \alpha \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v|^{\varphi(x)} \, dx - \frac{\beta}{2} \left(\int_{\Omega} |\nabla v|^{\varphi(x)} \, dx \right)^{2} + \int_{\Omega} \frac{1}{\psi(x)} |v|^{\psi(x)} \, dx - \lambda \int_{\Omega} H(x, v) \, dx, \\ &\geq \frac{\alpha}{\varphi_{s}} \int_{\Omega} |\nabla v|^{\varphi(x)} dx - \frac{\beta}{2\varphi_{l}^{2}} \left(\int_{\Omega} |\nabla v|^{\varphi(x)} \, dx \right)^{2} - \varepsilon \lambda \int_{\Omega} |v|^{\varphi(x)} \, dx - c_{\varepsilon} \lambda \int_{\Omega} |v|^{r(x)} \, dx \\ &\geq \left(\frac{\alpha}{\varphi_{s}} - c_{2} \lambda \varepsilon \right) \int_{\Omega} |\nabla v|^{\varphi(x)} \, dx - \frac{\beta}{2\varphi_{l}} \left(\int_{\Omega} |\nabla v|^{\varphi(x)} \, dx \right)^{2} - c_{\varepsilon} \lambda \left(||v||_{r(x)}^{r_{l}} + ||v||_{r(x)}^{r_{s}} \right) \\ &\geq \left(\frac{\alpha}{\varphi_{s}} - c_{2} \varepsilon \lambda \right) |||v|||^{\varphi_{s}} - \frac{\beta}{2\varphi_{l}^{2}} |||v|||^{2\varphi_{l}} - c_{\varepsilon} \lambda \left(c_{emb}^{r_{l}} |||v|||^{r_{l}} + c_{emb}^{r_{s}} |||v|||^{r_{l}}, \\ &\geq \left(\frac{\alpha}{\varphi_{s}} - c_{2} \varepsilon \lambda \right) |||v|||^{\varphi_{s}} - \frac{\beta}{2\varphi_{l}^{2}} |||v|||^{2\varphi_{l}} - c_{\varepsilon} \lambda \left(c_{emb}^{r_{l}} + c_{emb}^{r_{s}} \right) |||v|||^{r_{l}}, \end{split}$$

where embedding constant $c_{emb} > 0$. By selecting $\varepsilon \leq \frac{\alpha}{2c_2\varphi_*\lambda}$, we have

$$J_{\lambda}(v) \geq \frac{\alpha}{2\varphi_{s}} |||v|||^{\varphi_{s}} - \frac{\beta}{2\varphi_{s}^{2}} |||v|||^{2\varphi_{l}} - c_{\varepsilon} \lambda \left(c_{emb}^{r_{l}} + c_{emb}^{r_{s}}\right) |||v|||^{r_{l}}.$$



By dividing the previous inequality sides on the positive value $|||v|||^{\varphi_s}$ and since, we know that $\varphi_s < 2\varphi_l < r_l$, we have

$$J_{\lambda}(v) \geq |||v|||^{\varphi_s} \left[\frac{\alpha}{2\varphi_s} - \frac{\beta}{2\varphi_l^2} |||v|||^{2\varphi_l - \varphi_s} - c_{\varepsilon} \lambda \left(c_{emb}^{r_l} + c_{emb}^{r_s} \right) |||v|||^{r_l - \varphi_s} \right],$$

now, we can choose |||v||| = R > 0, such that

$$\frac{\alpha}{2\varphi_s} - \frac{\beta}{2\varphi_l^2} R^{2\varphi_l - \varphi_s} - c_{\varepsilon} \lambda \left(c_{emb}^{r_l} + c_{emb}^{r_s} \right) R^{r_l - \varphi_s} > 0. \tag{3.2}$$

We can infer that

$$c_{\varepsilon}\lambda\left(c_{emb}^{r_l}+c_{emb}^{r_s}\right)R^{r_l-\varphi_s}<\frac{\alpha}{2\varphi_s}-\frac{\beta}{2\varphi_l^2}R^{2\varphi_l-\varphi_s}=\frac{\alpha\varphi_l^2-\beta\varphi_sR^{2\varphi_l-\varphi_s}}{2\varphi_s\varphi_l^2},$$

since c_{ε} and $c_{emb} > 0$, we can infer that

$$\lambda < \frac{\alpha \varphi_l^2 - \beta \varphi_s R^{2\varphi_l - \varphi_s}}{2c_{\varepsilon} \left(c_{emb}^{r_l} + c_{emb}^{r_s}\right) \varphi_s \varphi_l^2 R^{r_l - \varphi_s}} := \lambda_0, \tag{3.3}$$

therefore, by (3.2) and (3.3) we have

$$\frac{\alpha}{2\varphi_s} - \frac{\beta}{2\varphi_l^2} R^{2\varphi_l - \varphi_s} - c_{\varepsilon} \lambda \left(c_{emb}^{r_l} + c_{emb}^{r_s} \right) R^{r_l - \varphi_s} > 0, \quad \forall \lambda \in (0, \lambda_0).$$

So, there exists $\delta > 0$ so that $J_{\lambda}(v) \geq \delta > 0$ for all $v \in X$ with |||v||| = R. Thus, the proof is complete.

Now, we prove that J_{λ} ensures the $(C)_c$ -condition.

Lemma 3.3. If $(\eta_1) - (\eta_4)$ hold, then for all $\lambda \geq 0$, J_{λ} ensures the $(C)_c$ -condition at any level $c \in \left(-\infty, \frac{\alpha^2}{2\beta}\right)$.

Proof. At the beginning, we consider the boundary condition for $\{v_n\}$, let $\{v_n\} \subset X$ be a $(C)_c$ sequence related to the J_{λ} , such that

$$J_{\lambda}(v_n) \to c \quad \text{and} \quad ||J'_{\lambda}(v_n)||_{X^*} (1 + |||v_n|||) \to 0.$$
 (3.4)

Using (η_3) and (3.4), we can write

$$\begin{split} \varphi_s c + O_n(1) &\geq \varphi_s J_\lambda(\upsilon_n) - \langle J_\lambda'(\upsilon_n), \upsilon_n \rangle \\ &= \alpha \int_\Omega \left(\frac{\varphi_s}{\varphi(x)} - 1 \right) |\nabla \upsilon_n|^{\varphi(x)} \, dx + \int_\Omega \left(\frac{\psi_s}{\psi(x)} - 1 \right) |\upsilon_n|^{\psi(x)} \, dx \\ &+ \lambda \int_\Omega \hat{H}(x, \upsilon_n) \, dx - \beta \left(\int_\Omega \frac{1}{\varphi(x)} |\nabla \upsilon_n|^{\varphi(x)} \, dx \right) \left(\int_\Omega \left[\frac{\varphi_s}{2\varphi(x)} - 1 \right] |\nabla \upsilon_n|^{\varphi(x)} \, dx \right). \end{split}$$



Since $\alpha \geq \beta$ and $2\varphi_i > \varphi_s$ we have

$$\begin{split} \varphi_s c + O_n(1) &\geq \beta \left(\frac{1}{\varphi_s} - \frac{1}{2\varphi_l} \right) \left(\int_{\Omega} |\nabla v_n|^{\varphi(x)} \, dx \right)^2 + \int_{\Omega} \left(\frac{\psi_s}{\psi(x)} - 1 \right) |v_n|^{\psi(x)} \, dx \\ &+ \lambda \int_{\Omega} (\hat{H}(x,0) - c_0) \, dx \\ &\geq \beta \left(\frac{1}{\varphi_s} - \frac{1}{2\varphi_l} \right) |||v_n|||^{2\varphi_l} + \int_{\Omega} \left(\frac{\psi_s}{\psi(x)} - 1 \right) |v_n|^{\psi(x)} \, dx \\ &+ \lambda \int_{\Omega} (\hat{H}(x,0) - c_0) \, dx, \end{split}$$

therefore

$$\varphi_{s}c + O_{n}(1) \ge \beta \left(\frac{1}{\varphi_{s}} - \frac{1}{2\varphi_{l}}\right) |||v_{n}|||^{2\varphi_{l}} + \int_{\Omega} \left(\frac{\psi_{s}}{\psi(x)} - 1\right) |v_{n}|^{\psi(x)} dx + \lambda \int_{\Omega} (\hat{H}(x, 0) - c_{0}) dx.$$

Since $\lambda \geq 0$, we have

$$\varphi_s c + O_n(1) \ge \beta \left(\frac{1}{\varphi_s} - \frac{1}{2\varphi_l}\right) |||v_n|||^{2\varphi_l} - \lambda c_0 |\Omega|,$$

thus

$$\beta \left(\frac{1}{\varphi_s} - \frac{1}{2\varphi_l} \right) |||v_n|||^{2\varphi_l} \le \varphi_s c + O_n(1) + \lambda c_0 |\Omega|.$$

Since $\varphi_s < 2\varphi_l$, $\beta > 0$ and $\lambda \ge 0$, it is clear that $\{v_n\}$ is bounded in X. Then

$$v_n \rightharpoonup v$$
 weakly in X . (3.5)

By Sobolev embedding (2.2), we have the following compact embedding

$$X \hookrightarrow L^{s(x)}(\Omega) \quad \text{for} \quad 1 \le s(x) < \varphi^*(x).$$
 (3.6)

From (3.5) and (3.6), we can infer that

$$v_n \rightharpoonup v$$
 in X , $v_n \to v$ in $L^{s(x)}(\Omega)$, $v_n(x) \to v(x)$, a.e. in Ω . (3.7)

Using Hölder inequality and (3.7), we have

$$\begin{split} \left| \int_{\Omega} |v_n|^{\psi(x) - 2} v_n(v_n - v) \, dx \right| &\leq \int_{\Omega} |v_n|^{\psi(x) - 1} |v_n - v| \, dx \\ &\leq \| |v_n|^{\psi(x) - 1} \|_{\frac{\psi(x)}{\psi(x) - 1}} \|v_n - v\|_{\psi(x)} \to 0 \quad \text{as} \quad n \to \infty, \end{split}$$

thus

$$\int_{\Omega} |v_n|^{\psi(x)-2} v_n(v_n - v) \, dx \to 0, \quad \text{as} \quad n \to \infty.$$
 (3.8)



By (η_1) and (η_2) , we have that for each $\varepsilon \in (0,1)$, there is $c_{\varepsilon} > 0$ so that

$$|\eta(x, \nu_n)| \le \varepsilon |\nu_n|^{\varphi(x) - 1} + c_{\varepsilon} |\nu_n|^{r(x) - 1}. \tag{3.9}$$

By Sobolev embedding (2.2), Hölder inequality and (3.9), we have

$$\left| \int_{\Omega} \eta(x, v_n) (v_n - v) \, dx \right| \leq \int_{\Omega} (\varepsilon |v_n|^{\varphi(x) - 1} |v_n - v| + c_{\varepsilon} |v_n|^{r(x) - 1} |v_n - v|) \, dx$$

$$\leq \varepsilon \||v_n|^{\varphi(x) - 1}\|_{\frac{\varphi(x)}{\varphi(x) - 1}} \|v_n - v\|_{\varphi(x)} + c_{\varepsilon} \varepsilon \||v_n|^{r(x) - 1}\|_{\frac{r(x)}{r(x) - 1}} \|v_n - v\|_{r(x)} \to 0,$$

as $n \to \infty$. Therefore

$$\int_{\Omega} \eta(x, \nu_n)(\nu_n - \nu) dx \to 0, \quad \text{as} \quad n \to \infty.$$
 (3.10)

From (3.4), we have $\langle J'_{\lambda}(v_n), v_n - v \rangle \to 0$, as $n \to \infty$, so, we can infer that

$$\left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v_n|^{\varphi(x)} dx\right) \int_{\Omega} |\nabla v_n|^{\varphi(x) - 2} \nabla v_n (\nabla v_n - \nabla v) dx
+ \int_{\Omega} |v_n|^{\psi(x) - 2} v_n (v_n - v) dx - \lambda \int_{\Omega} \eta(x, v_n) (v_n - v) dx \to 0.$$
(3.11)

From (3.8), (3.10), (3.11), we can write

$$\left(\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v_n|^{\varphi(x)} dx\right) \int_{\Omega} |\nabla v_n|^{\varphi(x) - 2} \nabla v_n (\nabla v_n - \nabla v) dx \to 0, \quad \text{as} \quad n \to \infty.$$
 (3.12)

Since $\{v_n\}$ is bounded in X, therefore, it is necessary for the following positive sequence to converge to a non-negative value such as v_p , which means,

$$\int_{\Omega} \frac{1}{\varphi(x)} |\nabla v_n|^{\varphi(x)} dx \to v_p \ge 0, \quad \text{as} \quad n \to \infty.$$

Similar to the proof of Lemma 3.1 in [23], we have the sequence $\left\{\alpha - \beta \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v_n|^{\varphi(x)} dx\right\}$ is bounded, when n is large enough. So, it follows from (3.12) that

$$\int_{\Omega} |\nabla v_n|^{\varphi(x)-2} \nabla v_n (\nabla v_n - \nabla v) \, dx \to 0,$$

as $n \to \infty$. So, by the (S_+) property (see Lemma 2.5), we get $|||v_n||| \to |||v|||$ (strongly) in X, that means J_{λ} ensures the $(C)_c$ -condition. Moreover, considering the proof of Lemma 3.1, Lemma 3.2 and Remark 3.1 in [23], we deduce that the $(C)_c$ -condition is satisfied for $c < \frac{\alpha^2}{2\beta}$.



3.1 Proof of Theorem 1.1

Proof. It is clear that $J_{\lambda}(0) = 0$, by Lemma 3.3, J_{λ} ensures the $(C)_c$ -condition where $c \in \left(-\infty, \frac{\alpha^2}{2\beta}\right)$. Considering Lemma 3.2, we prove that J_{λ} has the geometry of the Mountain pass theorem, thus, all the assumptions of Mountain pass theorem are satisfied, therefore, for each $\lambda < \lambda_0$, our problem has at least a nontrivial weak solution in X.

4 Proof of Theorem 1.2

In this section, we will prove that problem (1.1) has many pairs of solutions by using the following Symmetric Mountain pass theorem.

Theorem 4.1 ([8]). Let X be a real Banach space, and $J_{\lambda} \in C^1(X, \mathbb{R})$ that ensures the $(C)_c$ condition and $J_{\lambda}(0) = 0$ and J_{λ} be an even functional, such as

- (A) there exist two constants a, R > 0, so that $J_{\lambda}(v) \geq a$ for each $u \in X$ with |||v||| = R,
- (B) for each finite dimensional subspace $E \subset X$, there exists $R_E > 0$ so that $J_{\lambda}(v) \leq 0$ on $E \setminus B_R$.

Then J_{λ} has a sequence of critical points $\{v_n\}$ such that $J_{\lambda}(v_n) \to +\infty$.

It is clear that for the even functional J_{λ} , we have $J_{\lambda}(0) = 0$ and by Lemma 3.3, J_{λ} ensures the $(C)_c$ -condition where $c \in \left(-\infty, \frac{\alpha^2}{2\beta}\right)$. Therefore, it suffices to prove that the two conditions (A) and (B) of the Theorem 4.1 are true for the functional J_{λ} . On the other hand by the proof of Lemma 3.2 (a), where

$$a_0 = \frac{\alpha \varphi_l^2 - \beta \varphi_s R^{2\varphi_l - \varphi_s}}{2c_{\varepsilon} \left(c_{emb}^{r_l} + c_{emb}^{r_s}\right) \varphi_s \varphi_l^2 R^{r_l - \varphi_s}}$$

and $a = a_0 R^{\varphi_s}$ for each $\lambda \in (0, a_0)$, there is a > 0 so that for each $v \in X$ with |||v||| = R, we have $J_{\lambda}(v) \ge a > 0$. Thus, it suffices to consider only the condition (B).

We use the indirect proof method, thus assume that $\{v_n\} \subset E$ such that if $|||v_n||| \to +\infty$ as $n \to +\infty$, then there is $M \in \mathbb{R}$ so that it is a fixed constant, then

$$J_{\lambda}(v_n) \ge M, \quad \forall n \in \mathbb{N}.$$
 (4.1)

Now, for any $v_n \in E \subseteq X$, put $V_n := \frac{v_n}{|||v_n|||}$. It is clear that $|||V_n||| = 1$. On the other hand, since $\dim E < +\infty$, we have

$$\exists V \in E \setminus \{0\}; \quad |||V_n - V||| \to 0.$$

We can infer that

$$V_n(x) \to V(x)$$
 a.e. $x \in \Omega$, as $n \to \infty$,



since $V(x) \neq 0 \rightarrow |v_n(x)| \rightarrow +\infty$, as $n \rightarrow +\infty$, (by (4.1)).

By (η_3) , we can infer that

$$\lim_{n\to+\infty}\frac{H(x,\upsilon_n(x))}{|||\upsilon_n|||^{\varphi_s}}=\lim_{n\to+\infty}\frac{H(x,\upsilon_n(x))}{|\upsilon_n(x)|^{\varphi_s}}|V_n(x)|^{\varphi_s}=+\infty,$$

for all $x \in \Omega_0 := \{x \in \Omega : V(x) \neq 0\}$ and by (η_4) , there is s_0 , such that

$$\frac{H(x,s)}{|s|^{\varphi_s}} > 1, \quad \forall x \in \Omega \quad \text{and} \quad |s| > s_0.$$
(4.2)

Now by (η_1) , we can write

$$\exists C_2 > 0; \quad |H(x,s)| \le C_2, \quad \forall (x,s) \in \Omega \times [-s_0, s_0].$$
 (4.3)

Using (4.2) and (4.3), we conclude that

$$\exists C_4 \in \mathbb{R}, \quad H(x,s) \ge C_4, \quad \forall (x,s) \in \Omega \times \mathbb{R}.$$
 (4.4)

Thus

$$\frac{H(x, v_n) - C_4}{|||v_n|||^{\varphi_s}} \ge 0, \quad \forall x \in \Omega, \quad \forall n \in \mathbb{N}.$$

Then, we have

$$\frac{H(x, v_n)}{|v_n(x)|^{\varphi_s}} |V_n(x)|^{\varphi_s} - \frac{C_4}{|||v_n|||^{\varphi_s}} \ge 0, \quad \forall x \in \Omega, \quad \forall n \in \mathbb{N}.$$

$$(4.5)$$

Thus, by Poincaré inequality, (4.1) and (4.5), we can infer that

$$\begin{split} 0 & \leq \lim_{n \to +\infty} \frac{J_{\lambda}(\upsilon_n)}{|||\upsilon_n|||^{\varphi_s}} \\ & \leq \lim_{n \to +\infty} \left[\frac{\alpha \int_{\Omega} \frac{1}{\varphi(x)} |\nabla \upsilon_n|^{\varphi(x)} \, dx + \int_{\Omega} \frac{1}{\psi(x)} |\upsilon_n|^{\psi(x)} \, dx}{|||\upsilon_n|||^{\varphi_s}} - \lambda \int_{\Omega} \frac{H(x,\upsilon_n)}{|||\upsilon_n|||^{\varphi_s}} \, dx \right]. \end{split}$$

Since $\psi_s > \varphi_s$, and $\lambda > 0$, we have

$$\begin{split} 0 & \leq \lim_{n \to +\infty} \left[\frac{\alpha \int_{\Omega} \frac{1}{\varphi(x)} |\nabla v_n|^{\varphi(x)} \, dx}{|||v_n|||^{\varphi_s}} + \frac{\int_{\Omega} \frac{1}{\psi(x)} |v_n|^{\psi(x)} \, dx}{|||v_n|||^{\psi_s}} - \lambda \int_{\Omega} \frac{H(x, v_n)}{|||v_n|||^{\varphi_s}} \, dx \right] \\ & \leq \frac{\alpha}{\varphi_l} + \frac{C_5}{\psi_s} - \lambda \lim_{n \to +\infty} \int_{\Omega} \frac{H(x, v_n) - C_4}{|||v_n|||^{\varphi_s}} \, dx \\ & \leq \frac{\alpha}{\varphi_l} + \frac{C_5}{\psi_s} - \lambda \liminf_{n \to +\infty} \int_{\Omega_0} \frac{H(x, v_n) - C_4}{|||v_n|||^{\varphi_s}} \, dx \\ & \leq \frac{\alpha}{\varphi_l} + \frac{C_5}{\psi_s} - \lambda \liminf_{n \to +\infty} \int_{\Omega_0} \frac{H(x, v_n)}{|v_n(x)|^{\varphi_s}} |V_n(x)|^{\varphi_s} \, dx \to -\infty, \end{split}$$

which is a contradiction. Then, the proof of (B) in the Theorem 4.1 is complete.



4.1 Proof of Theorem 1.2

Proof. Now, by Theorem 4.1, we can deduce that J_{λ} has a sequence of critical points $\{v_n\}$ such that $J_{\lambda}(v_n) \to +\infty$, thus, we prove that our problem has infinitely many weak solutions and the Theorem 1.2 is proven.

Acknowledgement

The authors gratefully ackowledge the anonymous referees for their useful comments that lead to an improved version of the paper.



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