

## Totally umbilical proper slant submanifolds of para-Kenmotsu manifold

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### ABSTRACT

In this paper, we study slant submanifolds of a para-Kenmotsu manifold. We prove that totally umbilical slant submanifold of a para-Kenmotsu manifold is either invariant or anti-invariant or dimension of submanifold is 1 or the mean curvature vector  $H$  of the submanifold lies in the invariant normal subbundle.

### RESUMEN

En este paper estudiamos subvariedades inclinadas en variedades para-Kenmotsu. Demostramos que una subvariedad inclinada en una variedad para-Kenmotsu totalmente umbilical es invariante, o anti-invariante, o una subvariedad de dimensión 1, o el vector de curvatura media  $H$  de la subvariedad vive en el fibrado normal invariante.

**Keywords and Phrases:** para-Kenmotsu manifold; totally umbilical; slant submanifold.

**2010 AMS Mathematics Subject Classification:** 53C25, 53C40, 53D15.

## 1 Introduction

The study of submanifolds of an almost contact manifold is one of the utmost interesting topics in differential geometry. According to the behaviour of the tangent bundle of a submanifold with respect to action of the almost contact structure  $\phi$  of the ambient manifold, there are two well known classes of submanifolds, namely, invariant and anti-invariant submanifolds. Chen [4], introduced the notion of slant submanifolds of the almost Hermitian manifolds. The contact version of slant submanifolds were given by Lotta [12]. Since then many research articles have been appeared on the existence of different contact and lorentzian manifolds (See. [1, 3, 7, 14, 15]).

Motivated by the above studies, in the present paper we study slant submanifolds of almost para-Kenmotsu manifold and give a classification of results. Also we prove that totally umbilical slant submanifolds of para-Kenmotsu manifolds are totally geodesic.

The paper is organized as follows: In section 2, we review some basic concepts of para-Kenmotsu manifold and submanifold theory. Section 3 is the main section of this paper. In this section we give the classification result of totally umbilical slant submanifolds of para-Kenmotsu manifold. Further, we prove that totally umbilical slant submanifolds of a para-Kenmotsu manifold are totally geodesic.

## 2 Preliminaries

Let  $\tilde{M}$  be a  $(2m + 1)$ -dimensional smooth manifold,  $\phi$  a tensor field of type  $(1, 1)$ ,  $\xi$  a vector field and  $\eta$  a 1-form. We say that  $(\phi, \xi, \eta)$  is an almost para contact structure on  $\tilde{M}$  if [18]

$$\phi\xi = 0, \quad \eta \cdot \phi = 0, \quad \text{rank}(\phi) = 2m, \quad (2.1)$$

$$\phi^2 = I - \eta \otimes \xi, \quad \eta(\xi) = 1. \quad (2.2)$$

If an almost paracontact manifold admits a pseudo Riemannian metric  $g$  of signature  $(m + 1, m)$  satisfying

$$g(\phi \cdot, \phi \cdot) = -g + \eta \otimes \eta \quad (2.3)$$

called almost para contact metric manifold. Examples of almost para contact metric structure are given in [6] and [9].

Analogous to the definition of Kenmotsu manifold [10], Welyczko [17] introduced para-Kenmotsu structure for three dimensional normal almost para contact metric structures. The similar notion called p-Kenmotsu structure appears in the Sinha and Sai Prasad [16].

**Definition 2.1.** *An almost para contact metric manifold  $M(\phi, \xi, \eta, g)$  is para-Kenmotsu manifold if the Levi-Civita connection  $\tilde{\nabla}$  of  $g$  satisfies*

$$(\tilde{\nabla}_X \phi)Y = g(\phi X, Y)\xi - \eta(Y)\phi X, \quad (2.4)$$

for any  $X, Y \in \chi(M)$ , (where  $\chi(M)$  is the set of all differential vector fields on  $M$ ).

From (2.4), we have

$$\tilde{\nabla}_X \xi = X - \eta(X)\xi, \tag{2.5}$$

Assume  $M$  is a submanifold of a para-Kenmotsu manifold  $\tilde{M}$ . Let  $g$  and  $\nabla$  be the induced Riemannian metric and connections of  $M$ , respectively. Then the Gauss and Weingarten formulae are given respectively, by

$$\tilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y), \tag{2.6}$$

$$\tilde{\nabla}_X N = -A_N X + \nabla_X^\perp N, \tag{2.7}$$

for all  $X, Y$  on  $TM$  and  $N \in T^\perp M$ , where  $\nabla^\perp$  is the normal connection and  $A$  is the shape operator of  $M$  with respect to the unit normal vector  $N$ . The second fundamental form  $\sigma$  and the shape operator  $A$  are related by:

$$g(\sigma(X, Y), N) = g(A_N X, Y). \tag{2.8}$$

Now for any  $X \in \Gamma(TM)$  and  $V \in \Gamma(T^\perp M)$ , we write

$$\phi X = PX + FX, \tag{2.9}$$

$$\phi V = pV + fV. \tag{2.10}$$

For  $X, Y \in \Gamma(TM)$ , it is easy to observe from (2.1) and (2.9) that

$$g(PX, Y) = -g(X, PY). \tag{2.11}$$

The covariant derivatives of the endomorphisms  $\phi$ ,  $P$  and  $F$  are defined respectively as

$$(\tilde{\nabla}_X \phi)Y = \tilde{\nabla}_X \phi Y - \phi \tilde{\nabla}_X Y, \quad \forall X, Y \in \Gamma(T\tilde{M}), \tag{2.12}$$

$$(\tilde{\nabla}_X P)Y = \nabla_X PY - P \nabla_X Y, \quad \forall X, Y \in \Gamma(TM), \tag{2.13}$$

$$(\tilde{\nabla}_X F)Y = \nabla_X FY - F \nabla_X Y, \quad \forall X, Y \in \Gamma(TM). \tag{2.14}$$

The structure vector field  $\xi$  has been considered to be tangential to  $M$  throughout this paper, else  $M$  is simply anti-invariant [12]. Since  $\xi \in TM$ , for any  $X \in \Gamma(TM)$  by virtue of (2.5) and (2.6), we have

$$\nabla_X \xi = X - \eta(X)\xi \quad \text{and} \quad \sigma(X, \xi) = 0. \tag{2.15}$$

Making use of (2.4), (2.6), (2.7), (2.9), (2.10) and (2.12)-(2.14), we obtain

$$(\tilde{\nabla}_X P)Y = p\sigma(X, Y) + A_{FY}X + g(PX, Y)\xi - \eta(Y)PX, \tag{2.16}$$

$$(\tilde{\nabla}_X F)Y = f\sigma(X, Y) - \sigma(X, PY) - \eta(Y)FX. \tag{2.17}$$

A submanifold  $M$  of an almost para contact metric manifold  $\tilde{M}$  is said to be totally umbilical if

$$\sigma(X, Y) = g(X, Y)H, \tag{2.18}$$

where  $H$  is the mean curvature vector of  $M$ . Further  $M$  is totally geodesic if  $\sigma(X, Y) = 0$  and minimal if  $H = 0$ .

### 3 Slant submanifolds of an almost contact metric manifold

For any  $x \in M$  and  $X \in T_x M$  such that  $X, \xi$  are linearly independent, the angle  $\theta(x) \in [0, \frac{\pi}{2}]$  between  $\phi X$  and  $T_x M$  is a constant  $\theta$ , that is  $\theta$  does not depend on the choice of  $X$  and  $x \in M$ .  $\theta$  is called the slant angle of  $M$  in  $\tilde{M}$ . Invariant and anti-invariant submanifolds are slant submanifolds with slant angle  $\theta$  equal to  $0$  and  $\frac{\pi}{2}$ , respectively [5]. A slant submanifold which is neither invariant nor anti-invariant is called a proper slant submanifold.

We mention the following results for later use.

**Theorem 3.1.** [1] Let  $M$  be a submanifold of an almost contact metric manifold  $\tilde{M}$  such that  $\xi \in TM$ . Then,  $M$  is slant if and only if there exists a constant  $\lambda \in [0, 1]$  such that

$$P^2 = -\lambda(I - \eta \otimes \xi). \quad (3.1)$$

Further more, if  $\theta$  is the slant angle of  $M$ , then  $\lambda = \cos^2 \theta$ .

**Corollary 1.** [1] Let  $M$  be a slant submanifold of an almost contact metric manifold  $\tilde{M}$  with slant angle  $\theta$ . Then, for any  $X, Y \in TM$ , we have

$$g(PX, PY) = -\cos^2 \theta (g(X, Y) - \eta(X)\eta(Y)), \quad (3.2)$$

$$g(FX, FY) = -\sin^2 \theta (g(X, Y) - \eta(X)\eta(Y)). \quad (3.3)$$

**Theorem 3.2.** Let  $M$  be a totally umbilical slant submanifold of a para-Kenmotsu manifold  $\tilde{M}$ . Then either one of the following statements is true:

- (i)  $M$  is invariant;
  - (ii)  $M$  is anti-invariant;
  - (iii)  $M$  is totally geodesic;
  - (iv)  $\dim M = 1$ ;
  - (v) If  $M$  is proper slant, then  $H \in \Gamma(\mu)$ ;
- where  $H$  is the mean curvature vector of  $M$ .

*Proof.* Suppose  $M$  is totally umbilical slant submanifold, then we have

$$\sigma(PX, PX) = g(PX, PX)H = \cos^2 \theta \{-\|X\|^2 + \eta^2(X)\}H.$$

By virtue of (2.6), one can get

$$\cos^2 \theta \{-\|X\|^2 + \eta^2(X)\}H = \tilde{\nabla}_{PX} PX - \nabla_{PX} PX.$$

From (2.9), we have

$$\cos^2 \theta \{-\|X\|^2 + \eta^2(X)\}H = \tilde{\nabla}_{PX} \phi X - \tilde{\nabla}_{PX} FX - \nabla_{PX} PX.$$

Applying (2.7) and (2.12), we get

$$\cos^2\theta\{-\|X\|^2 + \eta^2(X)\}H = (\tilde{\nabla}_{PX}\phi)X + \phi\tilde{\nabla}_{PX}X + A_{FX}PX - \nabla_{PX}^\perp FX - \nabla_{PX}PX.$$

Using (2.4) and (2.6), we obtain

$$\begin{aligned} \cos^2\theta\{-\|X\|^2 + \eta^2(X)\}H &= g(\phi PX, X)\xi - \eta(X)\phi PX + \phi(\nabla_{PX}X + \sigma(X, PX)) \\ &\quad + A_{FX}PX - \nabla_{PX}^\perp FX - \nabla_{PX}PX. \end{aligned}$$

From (2.9), (2.11), (2.18) and the fact that  $X$  and  $PX$  are orthogonal vector fields on  $M$ , we arrive at

$$\begin{aligned} \cos^2\theta\{-\|X\|^2 + \eta^2(X)\}H &= -g(PX, PX)\xi - \eta(X)P^2X - \eta(X)FPX + P\nabla_{PX}X + F\nabla_{PX}X \\ &\quad + A_{FX}PX - \nabla_{PX}^\perp FX - \nabla_{PX}PX. \end{aligned}$$

Then applying (3.1) and (3.2), we obtain

$$\begin{aligned} \cos^2\theta\{-\|X\|^2 + \eta^2(X)\}H &= \cos^2\theta\{\|X\|^2 - \eta^2(X)\}\xi + \cos^2\theta\eta(X)\{X - \eta(X)\}\xi - \eta(X)FPX \\ &\quad + P\nabla_{PX}X + F\nabla_{PX}X + A_{FX}PX - \nabla_{PX}^\perp FX - \nabla_{PX}PX. \end{aligned} \quad (3.4)$$

Taking inner product with  $PX$  in (3.4), we get

$$0 = g(P\nabla_{PX}X, PX) + g(A_{FX}PX, PX) - g(\nabla_{PX}PX, PX). \quad (3.5)$$

By virtue of (3.2), the first term of (3.5) can be written as

$$g(P\nabla_{PX}X, PX) = -\cos^2\theta\{g(\nabla_{PX}X, X) - \eta(X)g(\nabla_{PX}X, \xi)\}. \quad (3.6)$$

We simplify the third term of (3.5) as follows

$$\begin{aligned} g(\nabla_{PX}PX, PX) &= g(\tilde{\nabla}_{PX}PX, PX) = \frac{1}{2}PXg(PX, PX). \\ &= \frac{1}{2}PX[-\cos^2\theta\{(g(X, X) - \eta^2(X))\}] \\ &= -\frac{1}{2}\cos^2\theta[PXg(X, X) - P(X)(g(X, \xi)g(X, \xi))] \\ &= -\frac{1}{2}\cos^2\theta[PXg(X, X) - 2\eta(X)P(X)g(X, \xi)] \\ &= -\frac{1}{2}\cos^2\theta[2g(\tilde{\nabla}_{PX}X, X) - 2\eta(X)\{g(\tilde{\nabla}_{PX}X, \xi) + g(X, \tilde{\nabla}_{PX}\xi)\}]. \end{aligned}$$

Using (2.5), (2.6), (3.6) and the fact that  $X$  and  $PX$  are orthogonal vector fields on  $M$ , we derive

$$\begin{aligned} g(\nabla_{PX}PX, PX) &= -\cos^2\theta[g(\nabla_{PX}X, X) - \eta(X)g(\nabla_{PX}X, \xi) \\ &\quad - \eta(X)g(X, PX - \eta(PX)\xi)] \\ &= -\cos^2\theta[g(\nabla_{PX}X, X) - \eta(X)g(\nabla_{PX}X, \xi)] \\ \rightarrow g(\nabla_{PX}PX, PX) &= g(P\nabla_{PX}X, PX). \end{aligned}$$

Using this fact in (3.5), we obtain

$$0 = g(A_{FX}PX, PX) = g(\sigma(PX, PX), FX).$$

As  $M$  is totally umbilical slant, then from (2.18) and (3.2), we obtain

$$0 = -\cos^2\theta\{\|X\|^2 - \eta^2(X)\}g(H, FX). \quad (3.7)$$

Thus from (3.7), we conclude that either  $\theta = \frac{\pi}{2}$  that is  $M$  is anti-invariant which part (ii) or the vector field  $X$  is parallel to the structure vector field  $\xi$ , i.e.,  $M$  is 1-dimensional submanifold which is fourth part of the theorem or  $H \perp FX$ , for all  $X \in \Gamma(TM)$ , i.e.,  $H \in \Gamma(\mu)$  which is the last part of the theorem or  $H = 0$ , i.e.,  $M$  is totally geodesic which is (iii) or  $FX = 0$ , i.e.,  $M$  is invariant which is part (i). This completes the proof of the theorem.  $\square$

**Theorem 3.3.** *Every totally umbilical proper slant submanifold of a para-Kenmotsu manifold is totally geodesic.*

*Proof.* Let  $M$  be a totally umbilical proper slant submanifold of a para-Kenmotsu manifold  $\tilde{M}$ , then for any  $X, Y \in \Gamma(TM)$ , we have

$$\tilde{\nabla}_X \phi Y - \phi \tilde{\nabla}_X Y = g(\phi X, Y)\xi - \eta(Y)\phi X.$$

Using equations (2.6) and (2.9), we get

$$\tilde{\nabla}_X PY + \tilde{\nabla}_X FY - \phi(\nabla_X Y + \sigma(X, Y)) = g(PX, Y)\xi - \eta(Y)PX - \eta(Y)FX.$$

Again from (2.6), (2.7) and (2.9), we obtain

$$\begin{aligned} g(PX, Y)\xi - \eta(Y)PX - \eta(Y)FX &= \nabla_X PY + \sigma(X, PY) - A_{FY}X \\ &\quad + \nabla_X^\perp FY - P\nabla_X Y - F\nabla_X Y - \phi\sigma(X, Y). \end{aligned}$$

As  $M$  is totally umbilical, then

$$\begin{aligned} g(PX, Y)\xi - \eta(Y)PX - \eta(Y)FX &= \nabla_X PY + g(X, PY)H - A_{FY}X + \nabla_X^\perp FY \\ &\quad - P\nabla_X Y - F\nabla_X Y - g(X, Y)\phi H. \end{aligned} \quad (3.8)$$

Taking the inner product with  $\phi H$  in (3.8) and from the fact that  $H \in \Gamma(\mu)$ , we obtain

$$g(\nabla_X^\perp FY, \phi H) = -g(X, Y)\|H\|^2.$$

Applying (2.7) and the property of Riemannian connection the above equation takes the form

$$g(FY, \nabla_X^\perp \phi H) = g(X, Y)\|H\|^2. \quad (3.9)$$

Now for any  $X \in \Gamma(TM)$ , we have

$$\tilde{\nabla}_X \phi H = (\tilde{\nabla}_X \phi)H + \phi \tilde{\nabla}_X H.$$

Using the fact  $H \in \Gamma(\mu)$  and by virtue of (2.4), (2.7) and (2.9), we obtain

$$-A_{\phi H}X + \nabla_X^\perp \phi H = -PA_HX - FA_HX + \phi \nabla_X^\perp H. \tag{3.10}$$

Also for any  $X \in \Gamma(TM)$ , we have

$$g(\nabla_X^\perp H, FX) = g(\tilde{\nabla}_X H, FX) = -g(H, \tilde{\nabla}_X FX).$$

Using (2.9), we obtain

$$g(\nabla_X^\perp H, FX) = -g(H, \tilde{\nabla}_X \phi X) + g(H, \tilde{\nabla}_X PX).$$

Further from (2.6) and (2.12), we derive

$$g(\nabla_X^\perp H, FX) = -g(H, (\tilde{\nabla}_X \phi)X) - g(H, \phi \tilde{\nabla}_X X) + g(H, \sigma(X, PX)).$$

Using (2.4) and (2.18), the first and last term of right hand side of the above equation are identically zero and hence by (2.3), the second term gives

$$g(\nabla_X^\perp H, FX) = g(\phi H, \tilde{\nabla}_X X).$$

Again by using (2.6) and (2.18), we obtain

$$g(\nabla_X^\perp H, FX) = g(\phi H, H)\|X\|^2 = 0.$$

This means that

$$\nabla_X^\perp H \in \Gamma(\mu). \tag{3.11}$$

Now, taking the inner product in (3.10) with  $FY$  for any  $Y \in \Gamma(TM)$ , we get

$$g(\nabla_X^\perp \phi H, FY) = -g(FA_HX, FY) + g(\phi \nabla_X^\perp H, FY).$$

Using (3.11) and from (3.3) and (3.9), we obtain

$$g(X, Y)\|H\|^2 = \sin^2\theta\{g(A_HX, Y) - \eta(Y)g(A_HX, \xi)\}. \tag{3.12}$$

Hence by (2.8) and (2.18), the above equation reduces to

$$g(X, Y)\|H\|^2 = \sin^2\theta\{g(X, Y)\|H\|^2 - \eta(Y)g(\sigma(X, Y), H)\}. \tag{3.13}$$

Since for a para-Kenmotsu manifold  $\tilde{M}$ ,  $\sigma(X, \xi) = 0$  for any  $X$  tangent to  $\tilde{M}$ , thus we obtain

$$g(X, Y)\|H\|^2 = \sin^2\theta\{g(X, Y)\|H\|^2\}.$$

Therefore, the above equation can be written as

$$\cos^2\theta g(X, Y)\|H\|^2 = 0. \tag{3.14}$$

Since  $M$  is proper slant submanifold, thus from (3.14) we conclude that  $H = 0$ , i.e.,  $M$  is totally geodesic in  $\tilde{M}$ . This completes the proof.  $\square$

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